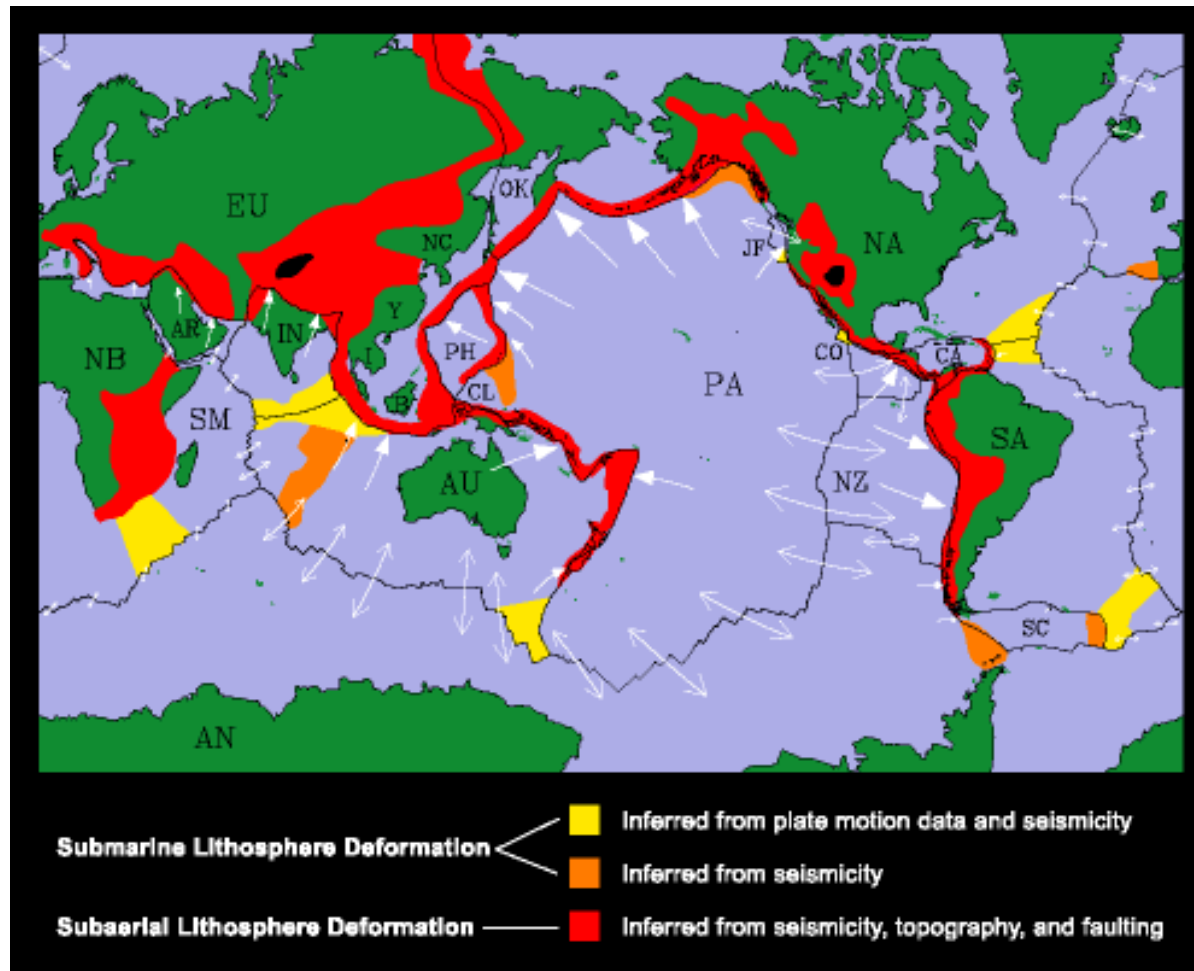


Lecture 9: Plate Boundary Zones

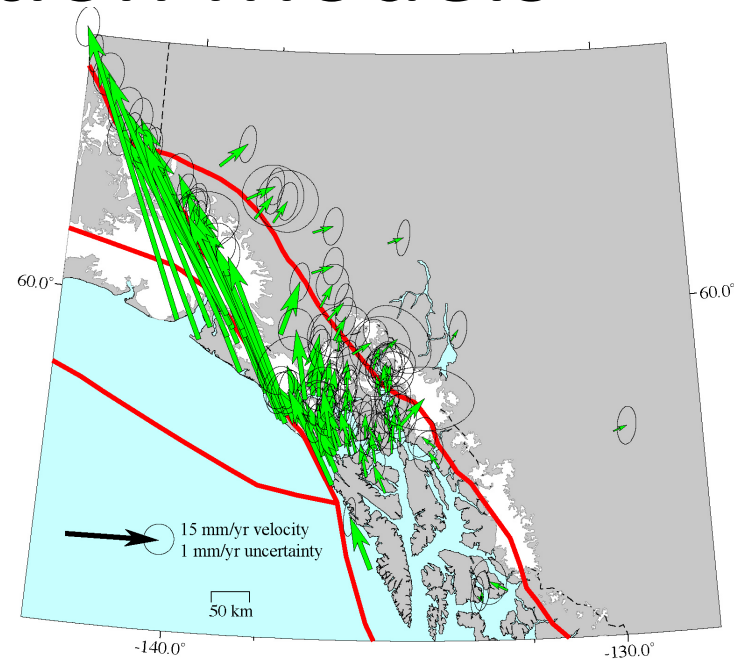
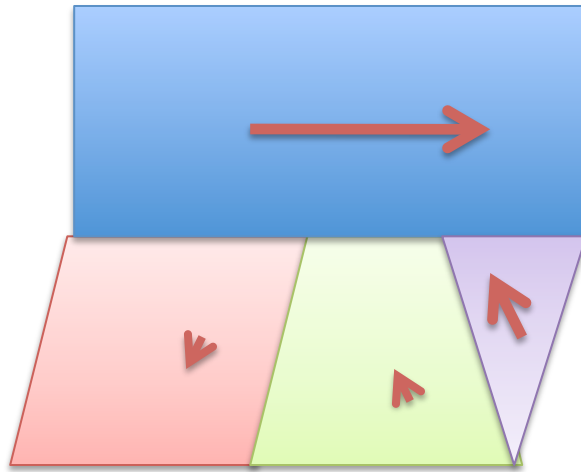


GEOS 655 Tectonic Geodesy
Jeff Freymueller, UAF

Most Plate Boundaries Complex

- Distributed deformation at plate boundaries is common. In continental crust, narrow boundaries are the exception, not the rule.
- Many broad plate boundary zones are made up of small blocks or microplates. In some regions, deformation is either quasi-uniform or the blocks are numerous and very small.
- Identification of microplate boundaries and motions is complicated by the elastic deformation associated with locked faults (a topic we will come back to in detail later in the course).

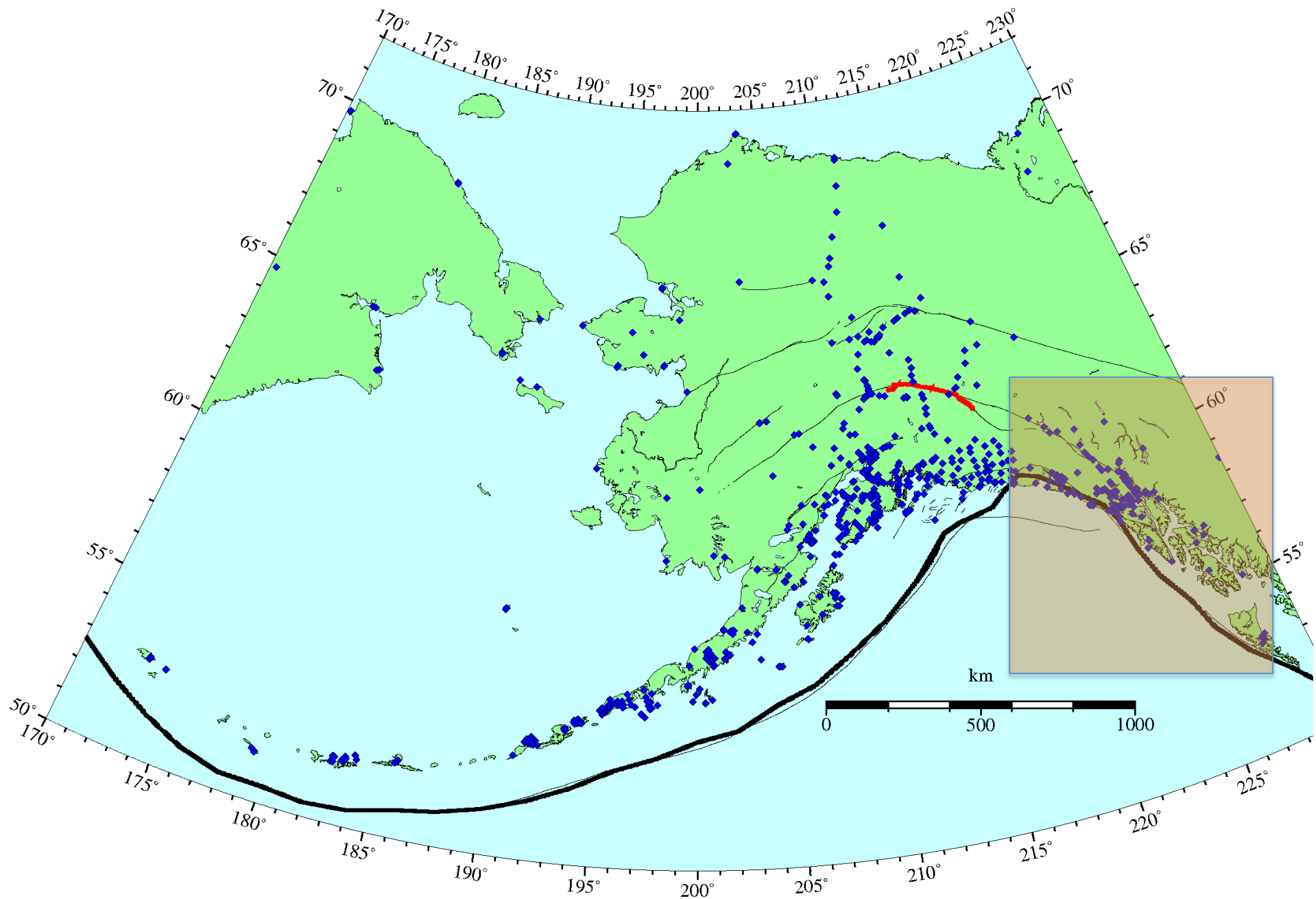
Block Motion Models



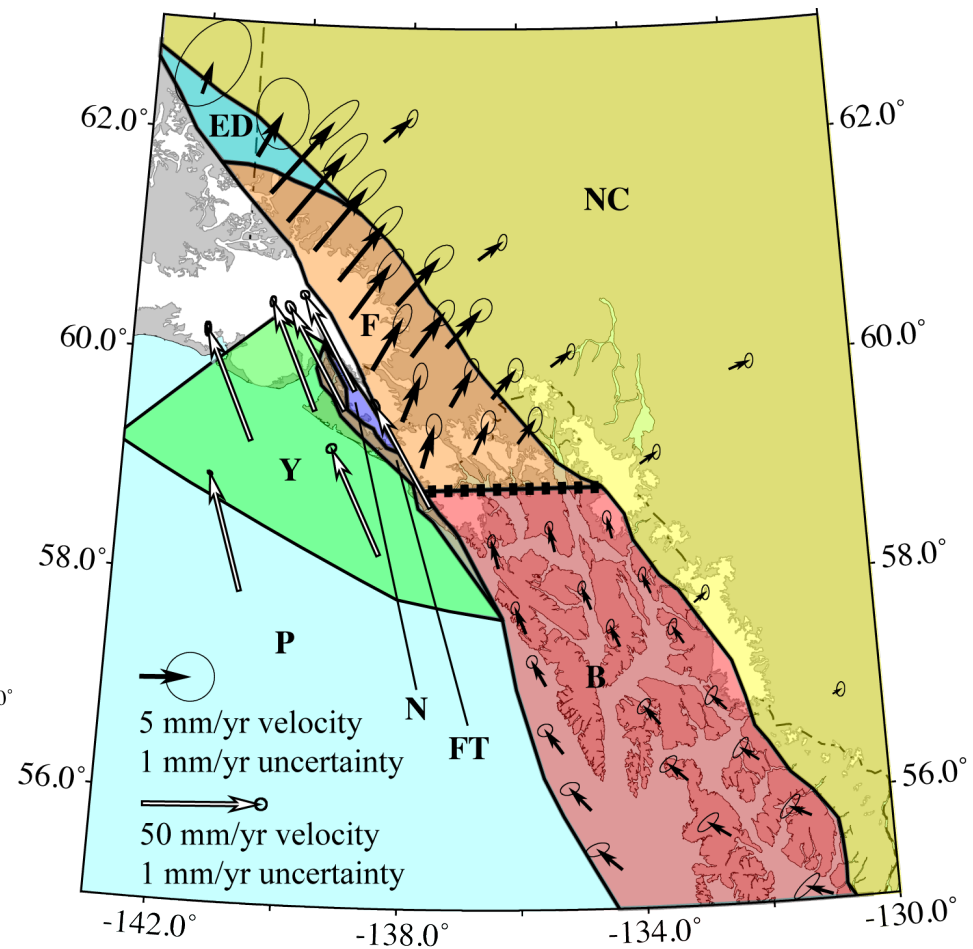
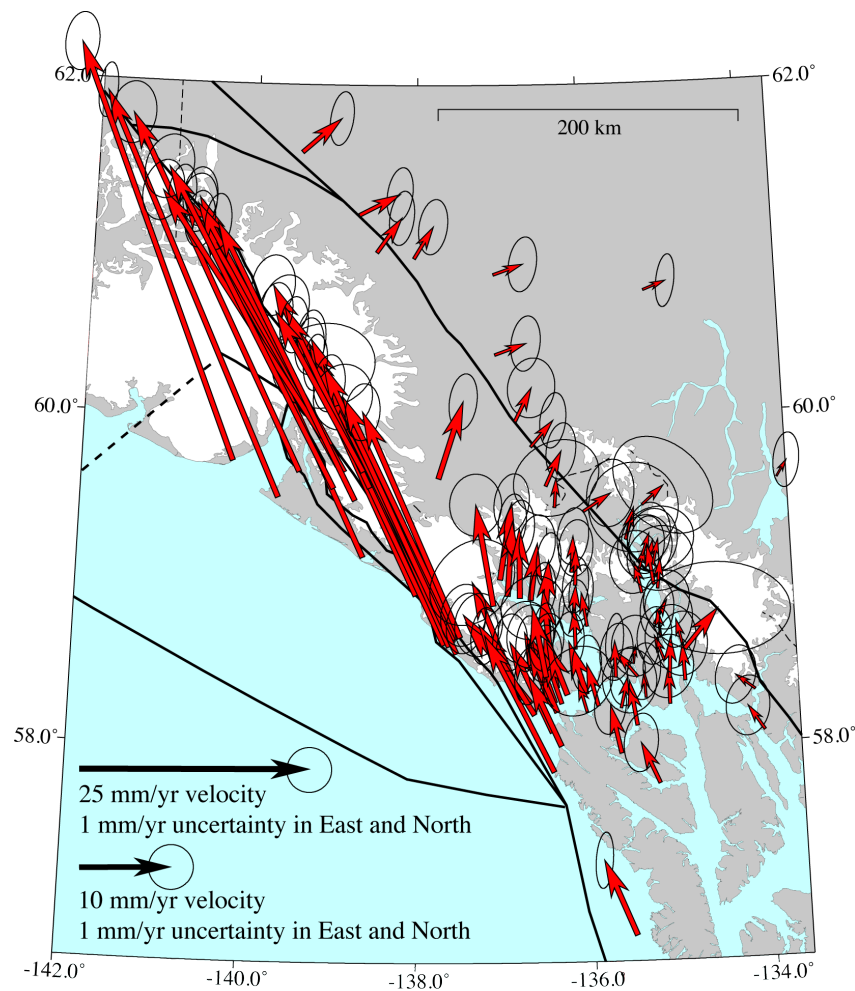
Key Elements

- Blocks usually assumed to be rigid
- Provide a means to separate elastic deformation from locked faults from long-term motions
- Enforces self-consistency in estimates of fault slip rates

Southeast Alaska Block Model

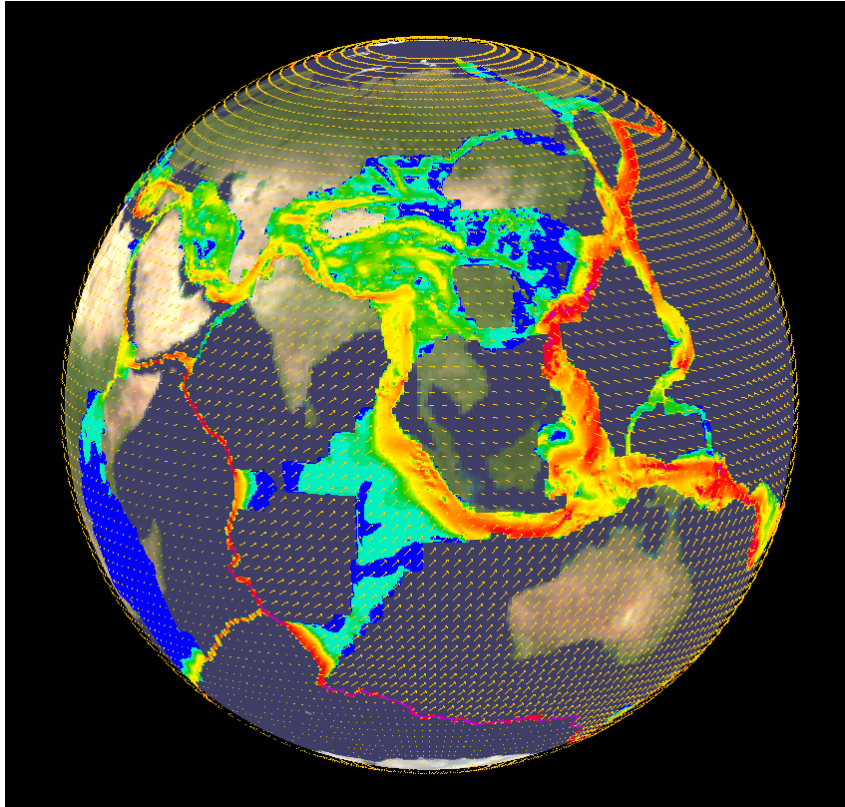


Block Model for SE Alaska



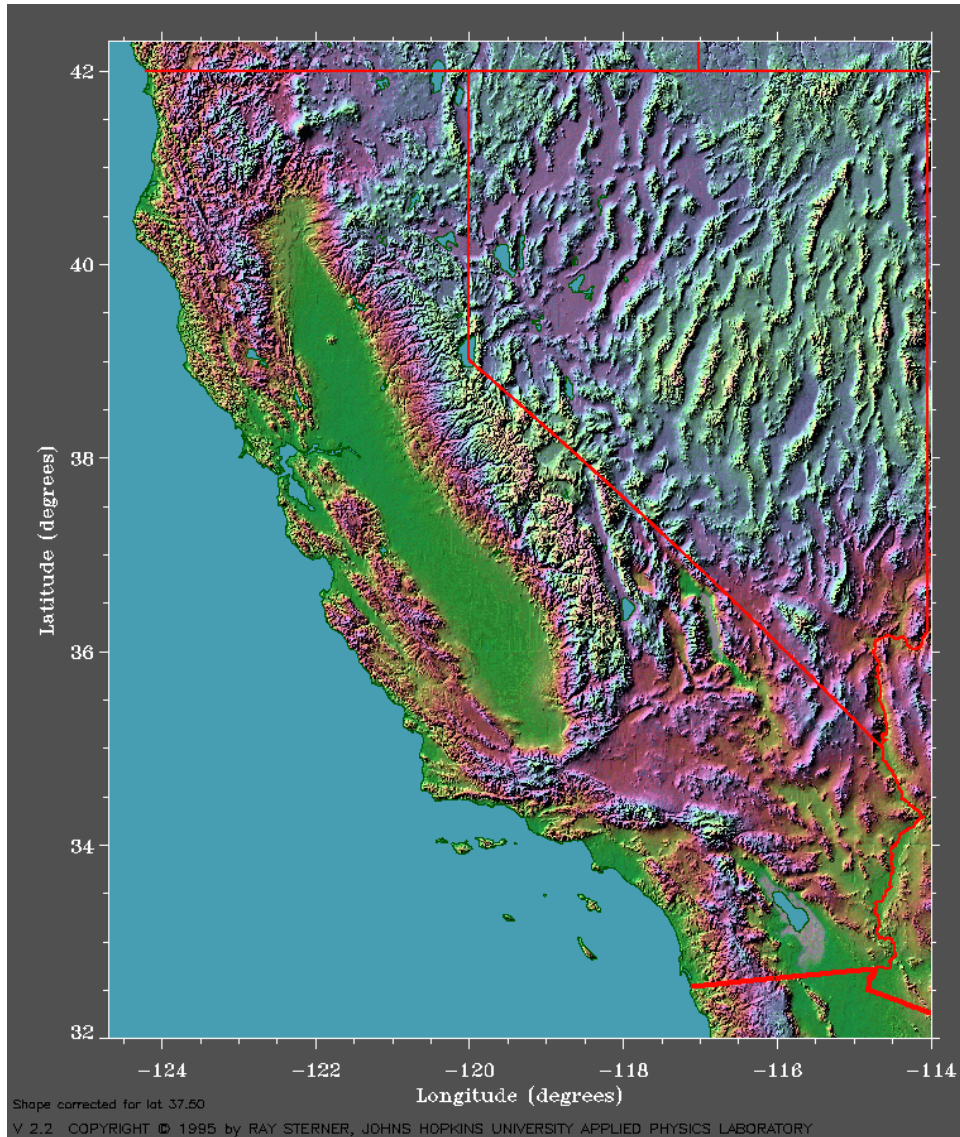
Elliott et al. (2010, JGR)

Global Strain Rate Map



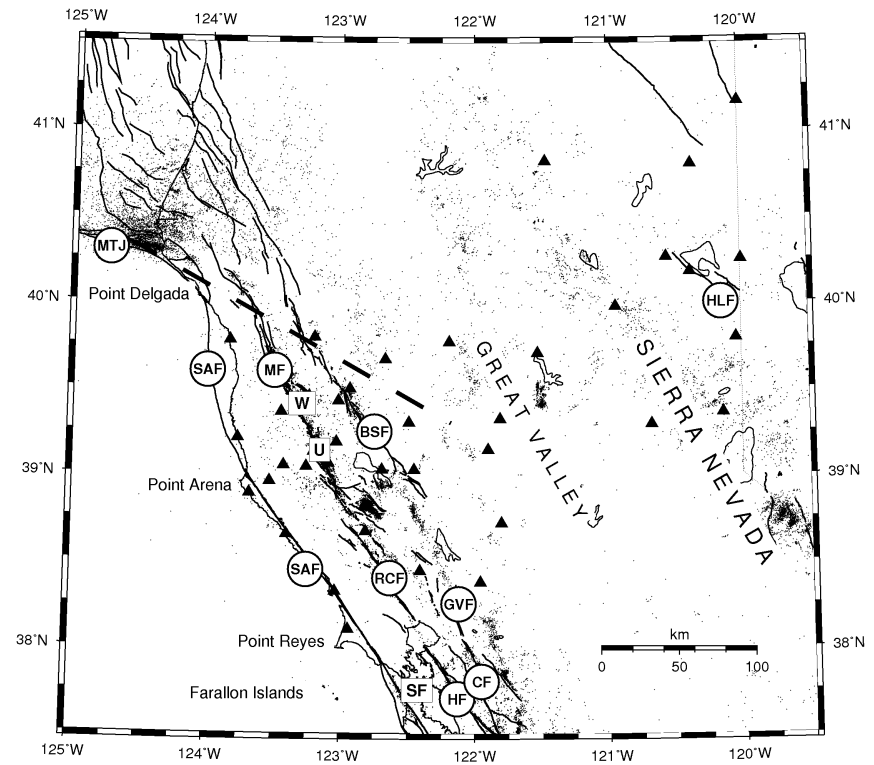
- An example of a product derived from GPS velocity field.
 - Rigid plate regions are shown with velocity grids to show motion.
 - Color coding shows magnitude of strain, a key measure of deformation.
 - We'll develop the mathematical basis for strain calculations starting next lecture.

Slip Partitioned System



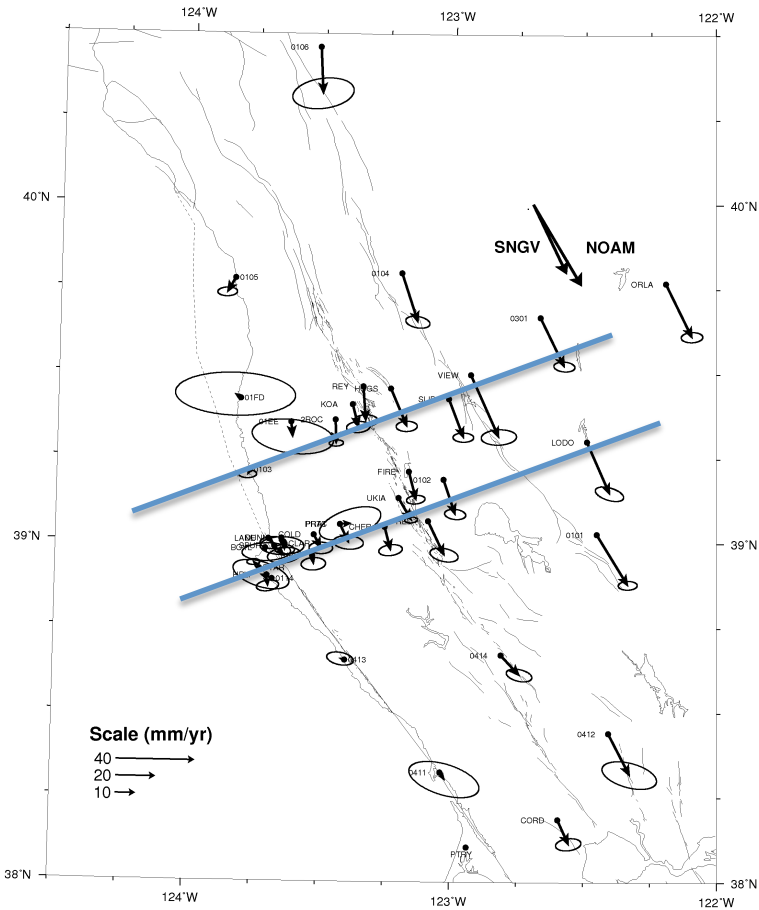
- Sierra Nevada-Great Valley (SNGV) block is stable
- Pure strike-slip west of SNGV
- Extension east of SNGV
- Also strike slip on eastern edge of SNGV

A “Simple” Plate Boundary Zone

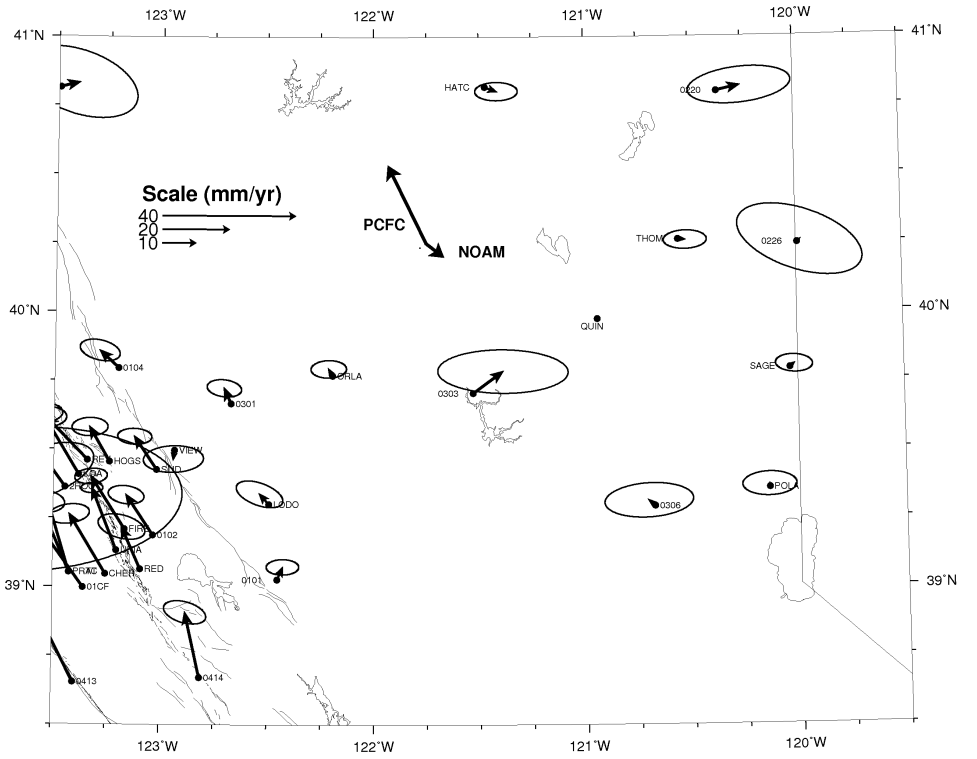


GMT Nov 5 15:17 Figure 1, Freymueller et al.

Northern California Velocity Field

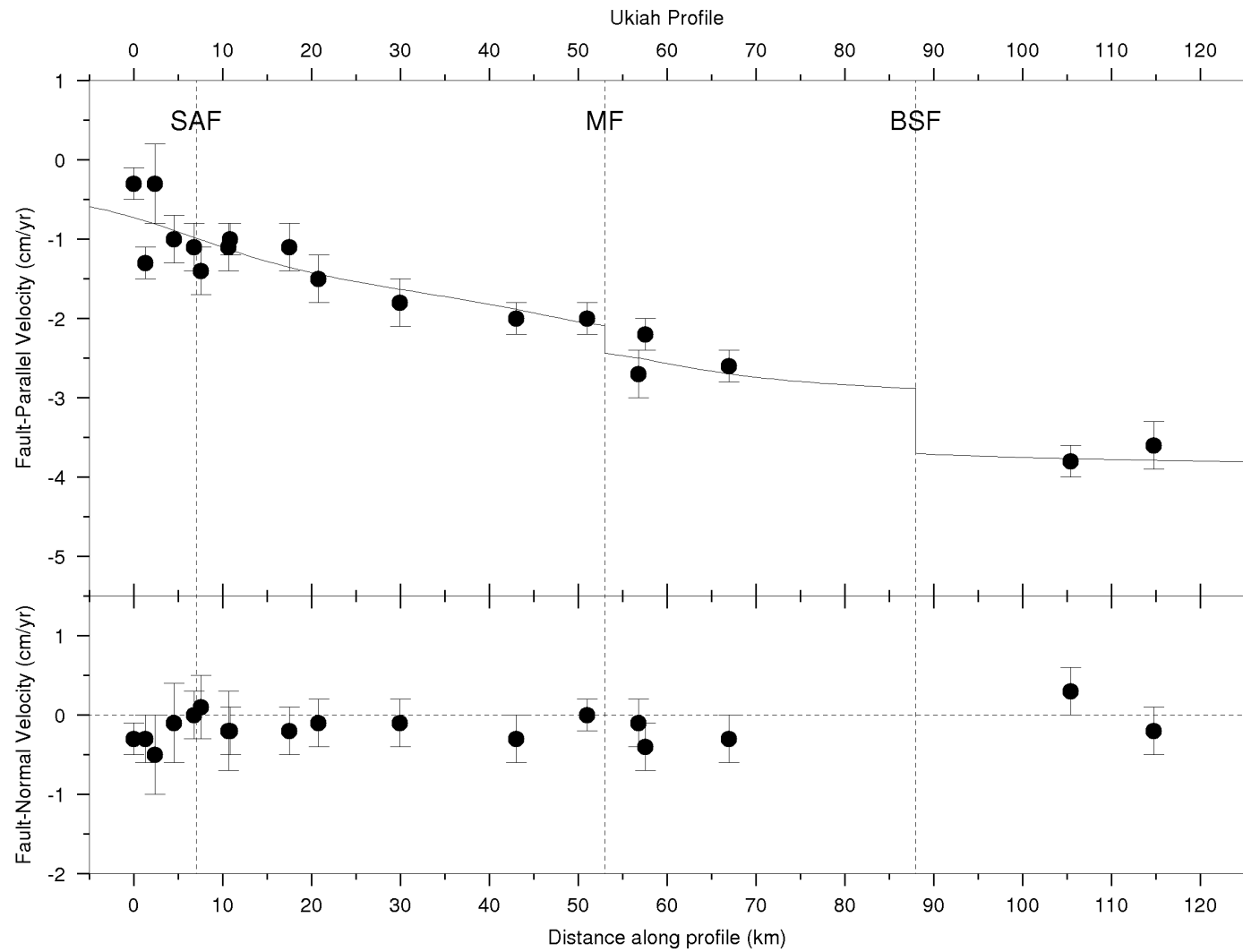


GMT Apr 6 14:18 Figure 3, Freymueller et al.

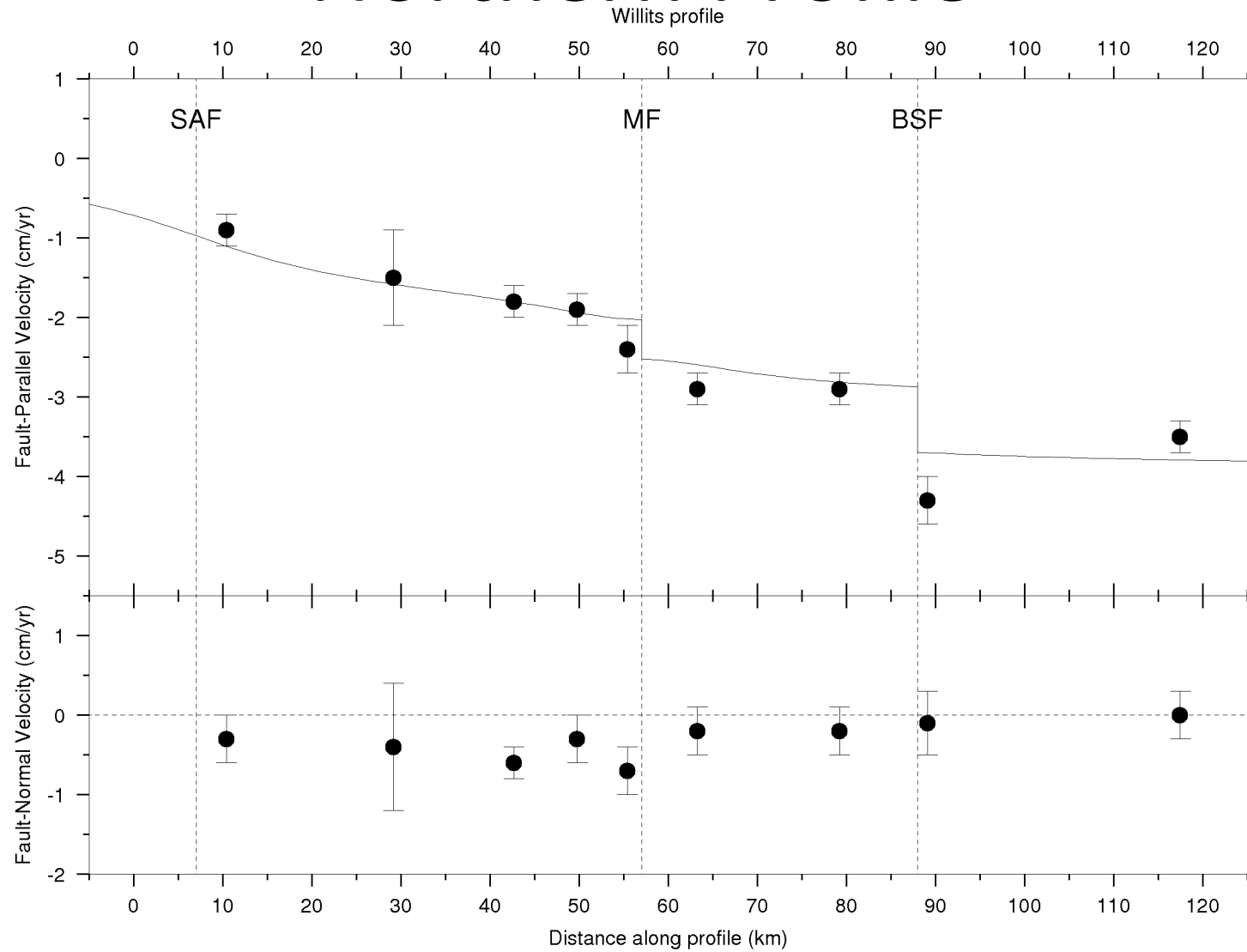


GMT Apr 6 14:36 Figure 4, Freymueller et al.

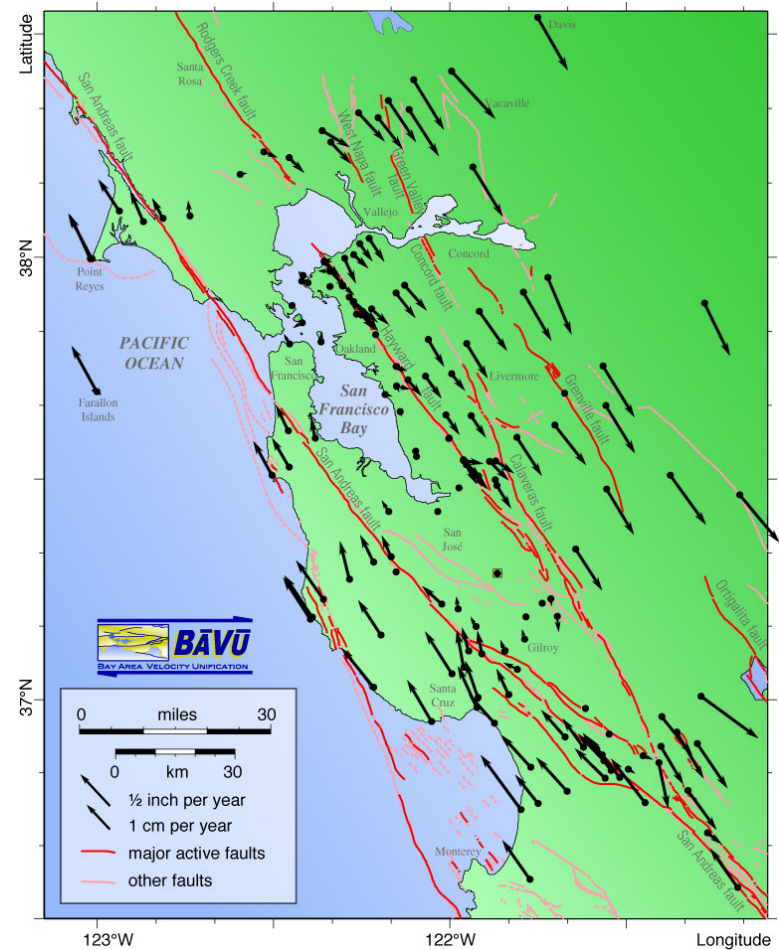
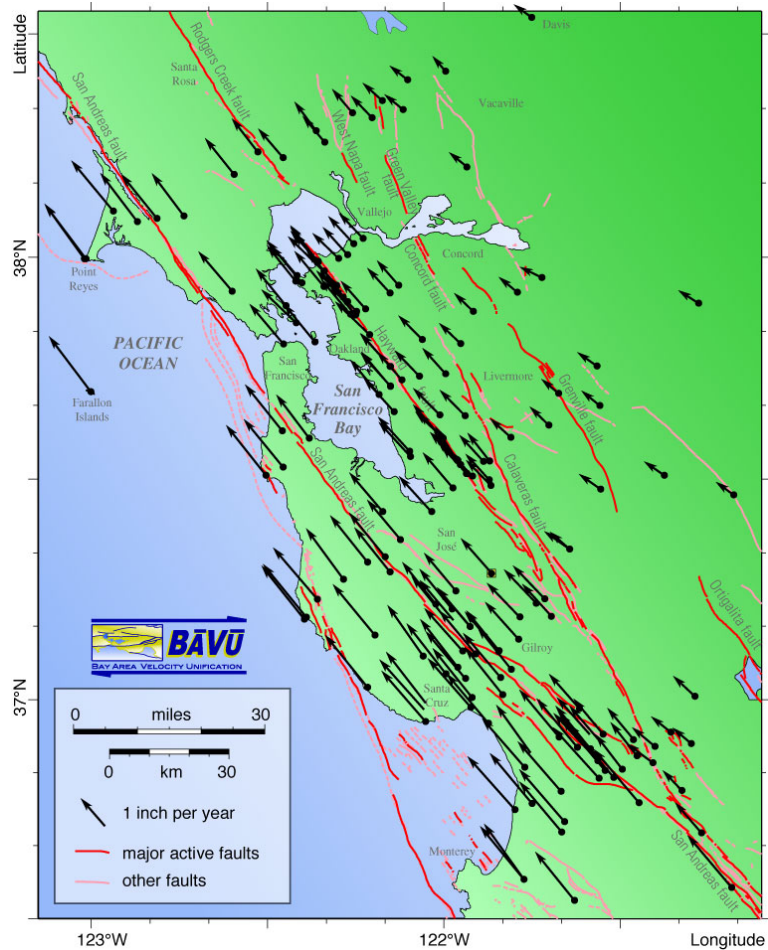
Southern Profile



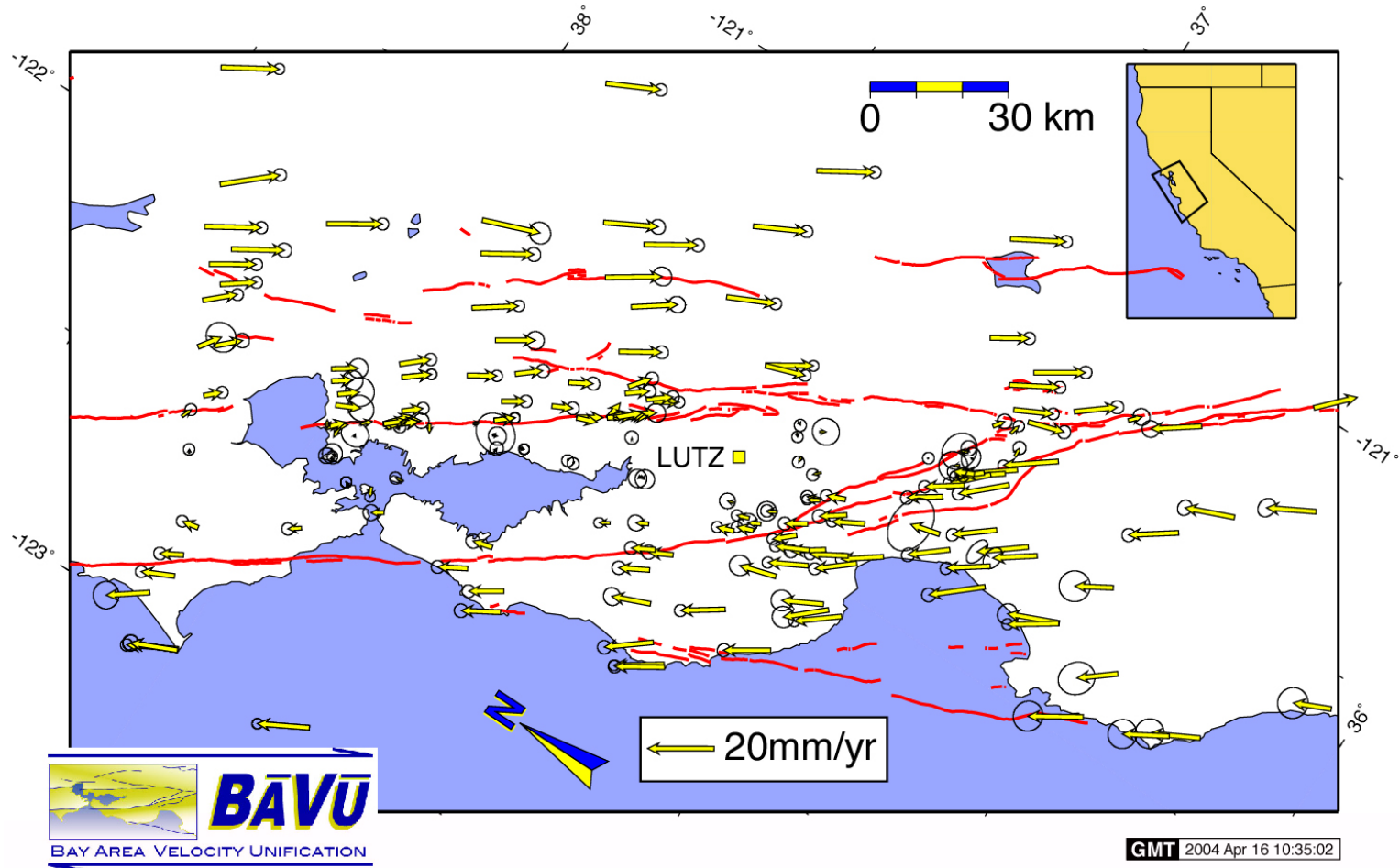
Northern Profile



SF Bay Area

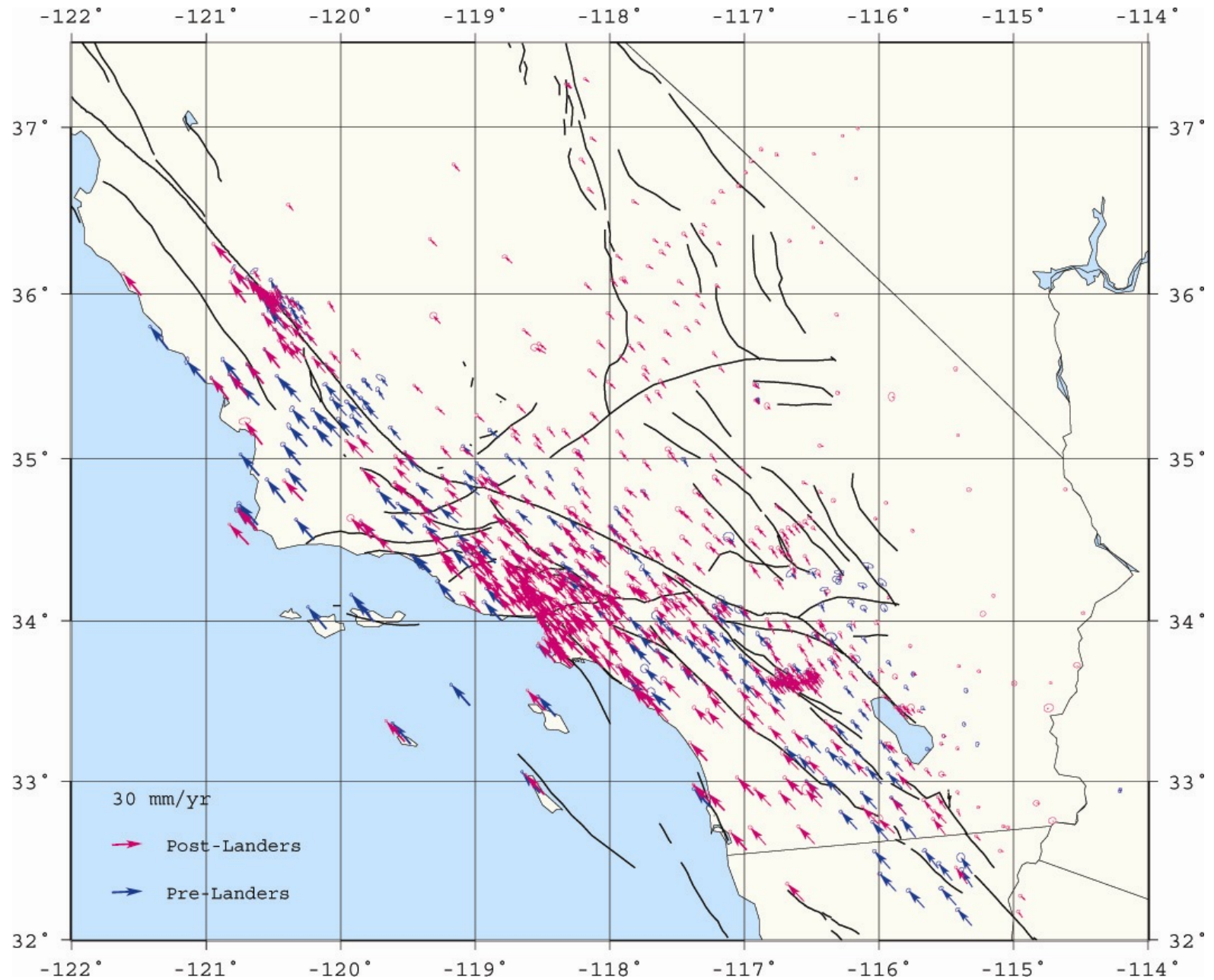


Block Model



d' Alessio et al. (2005, JGR), doi: 10.1029/2004JB003496

Example: Strain rate estimation from SCEC CMM3 (Post-Landers)



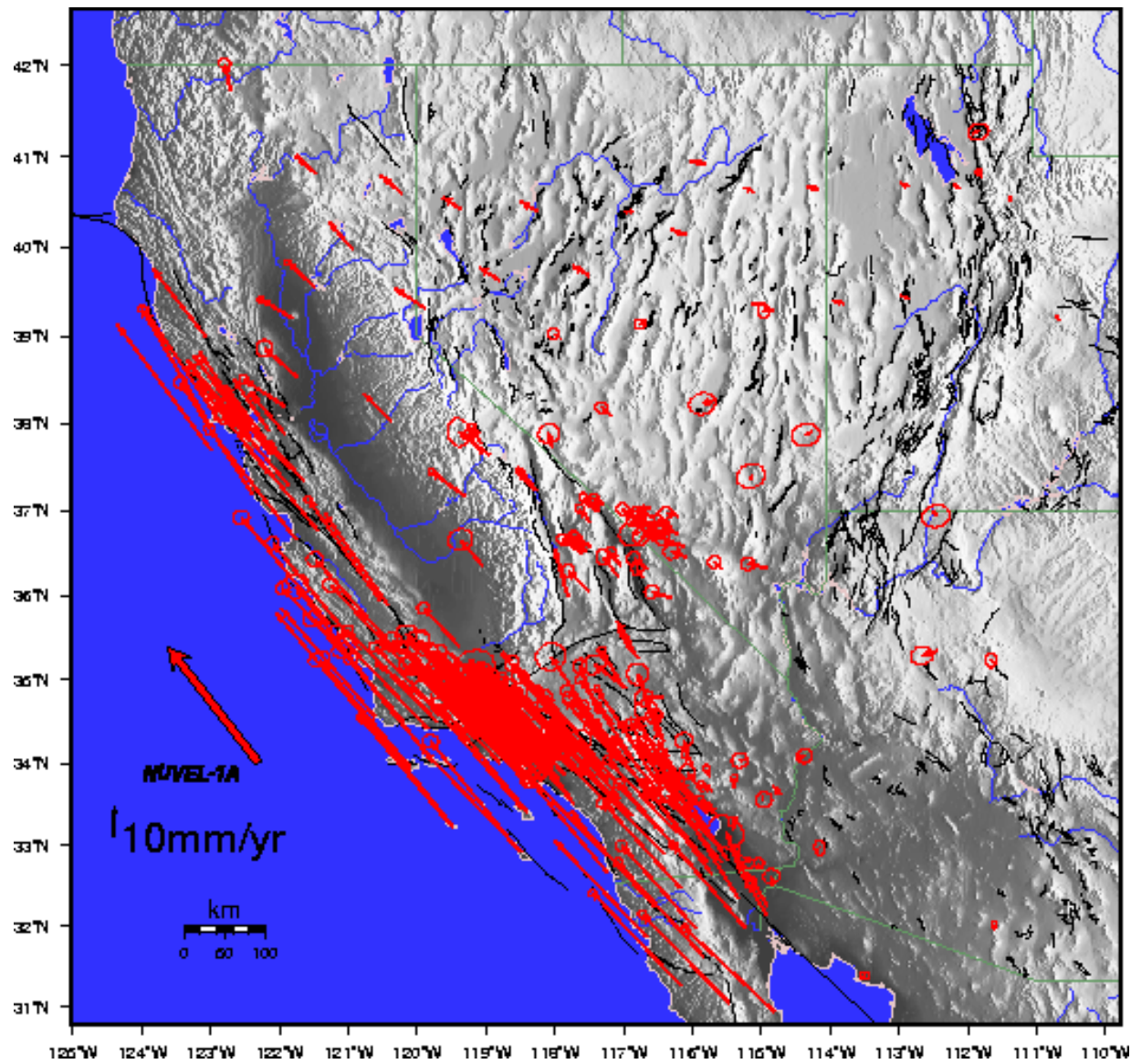
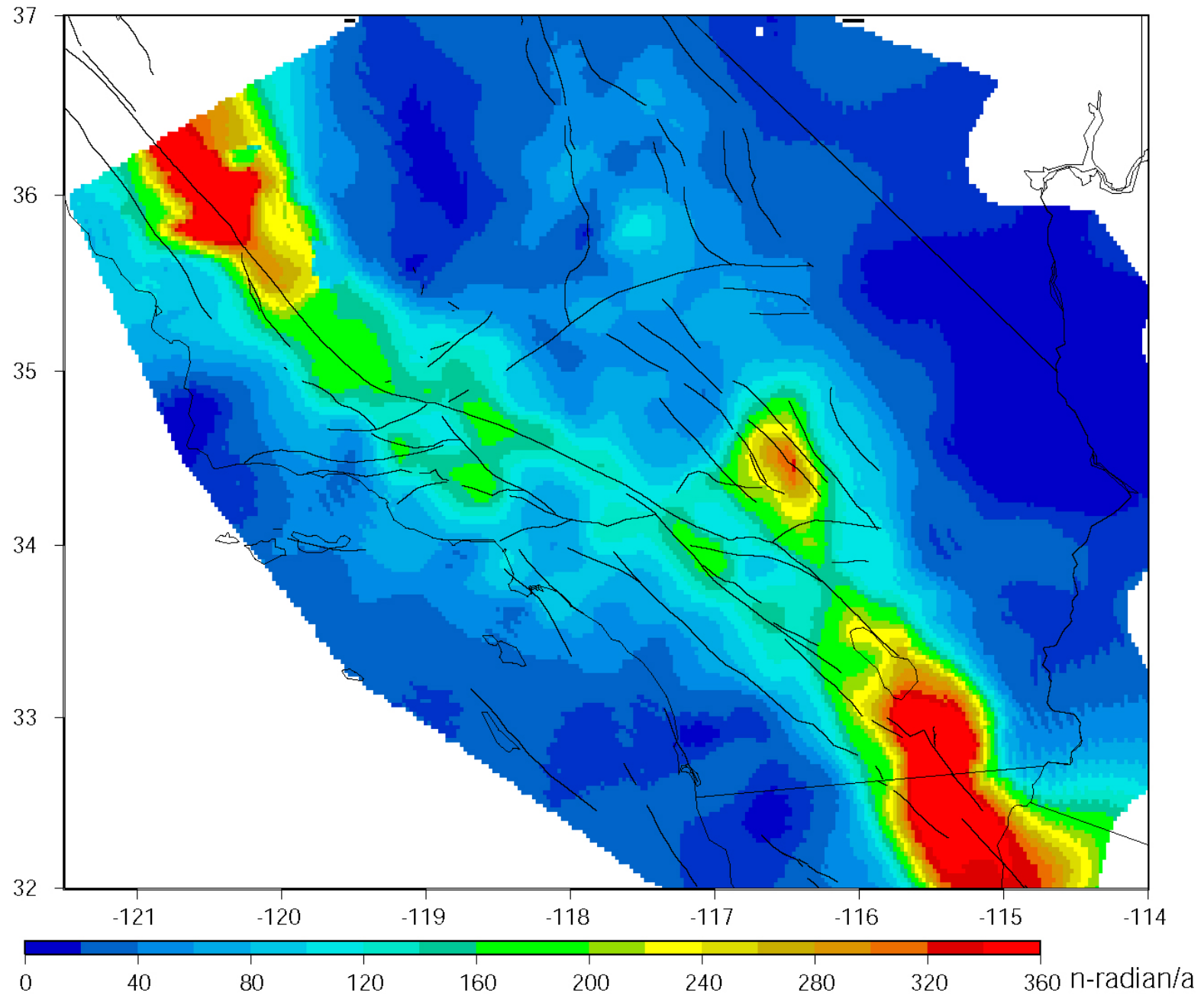
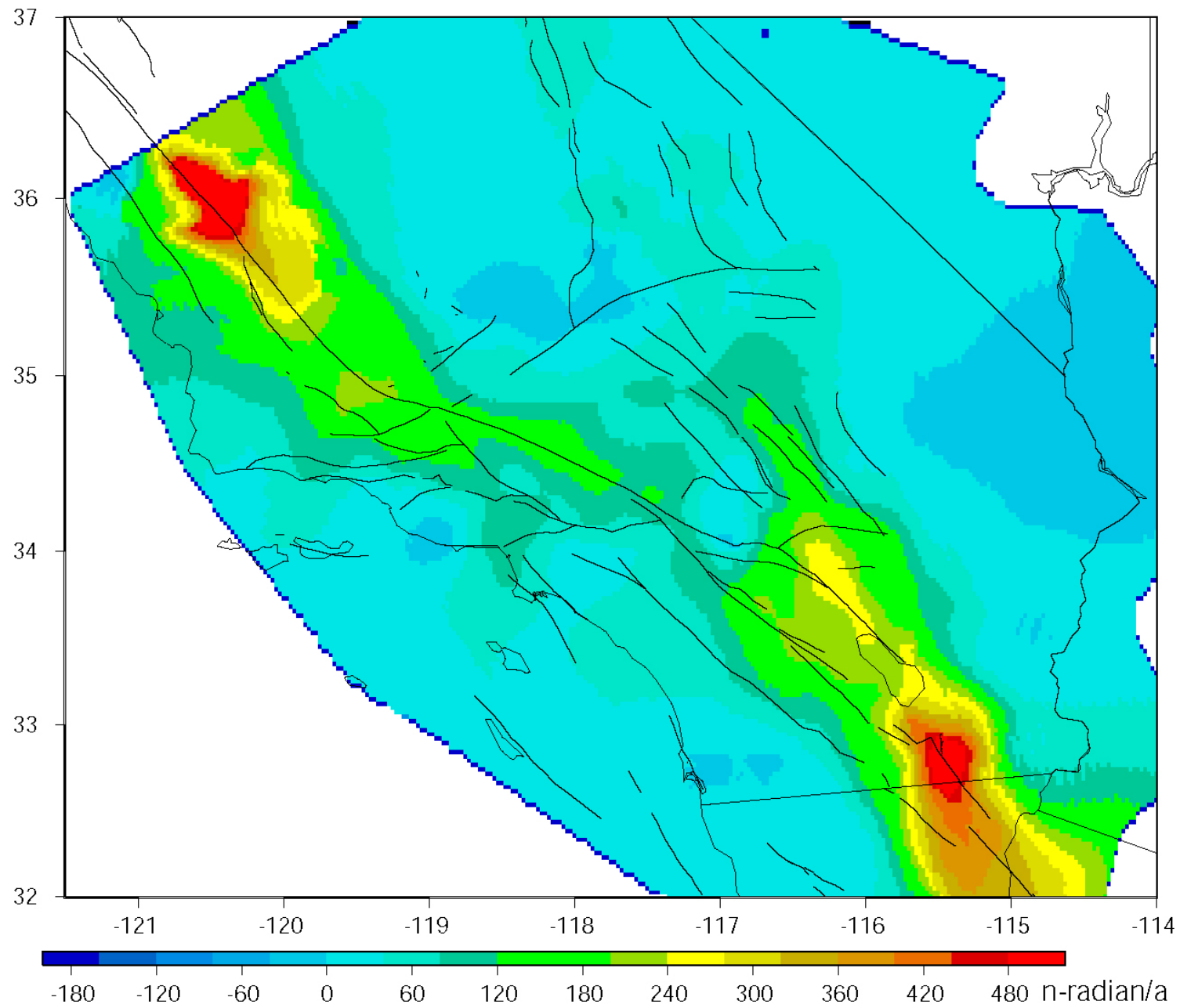


Figure from R. Bennett (website)

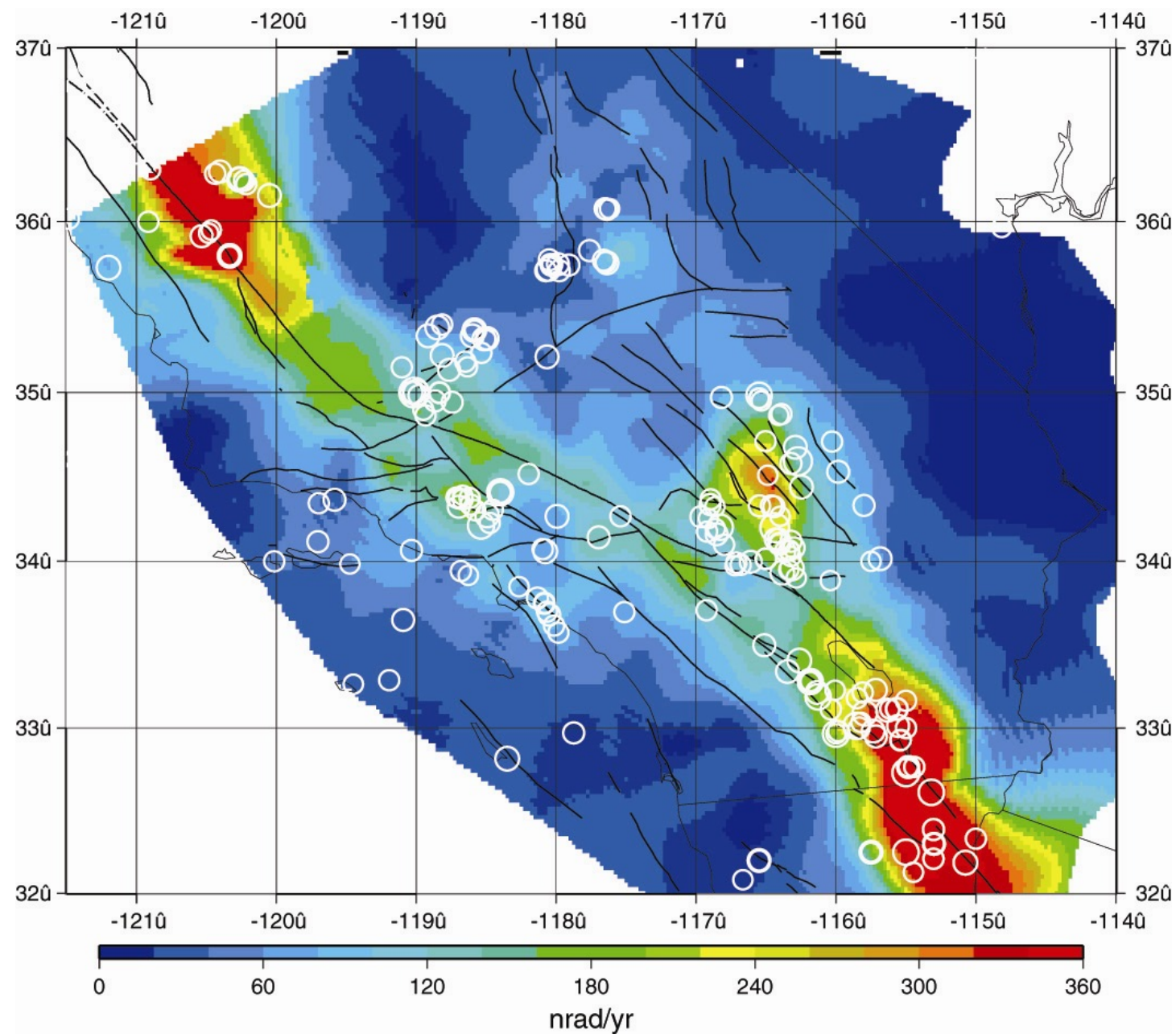
Post-Landers Maximum Shear Strain Rate



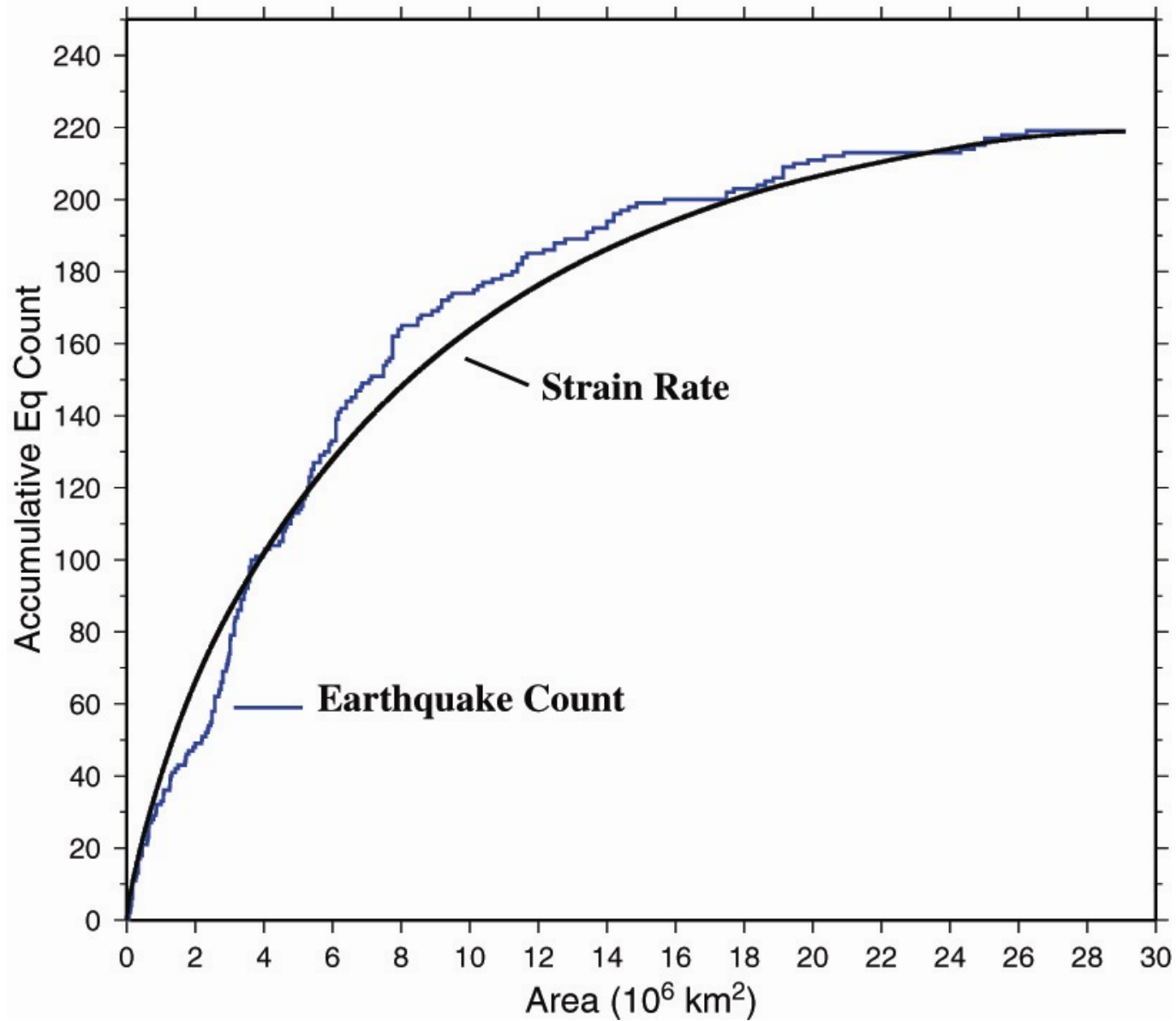
Post-Landers Rotation Rate



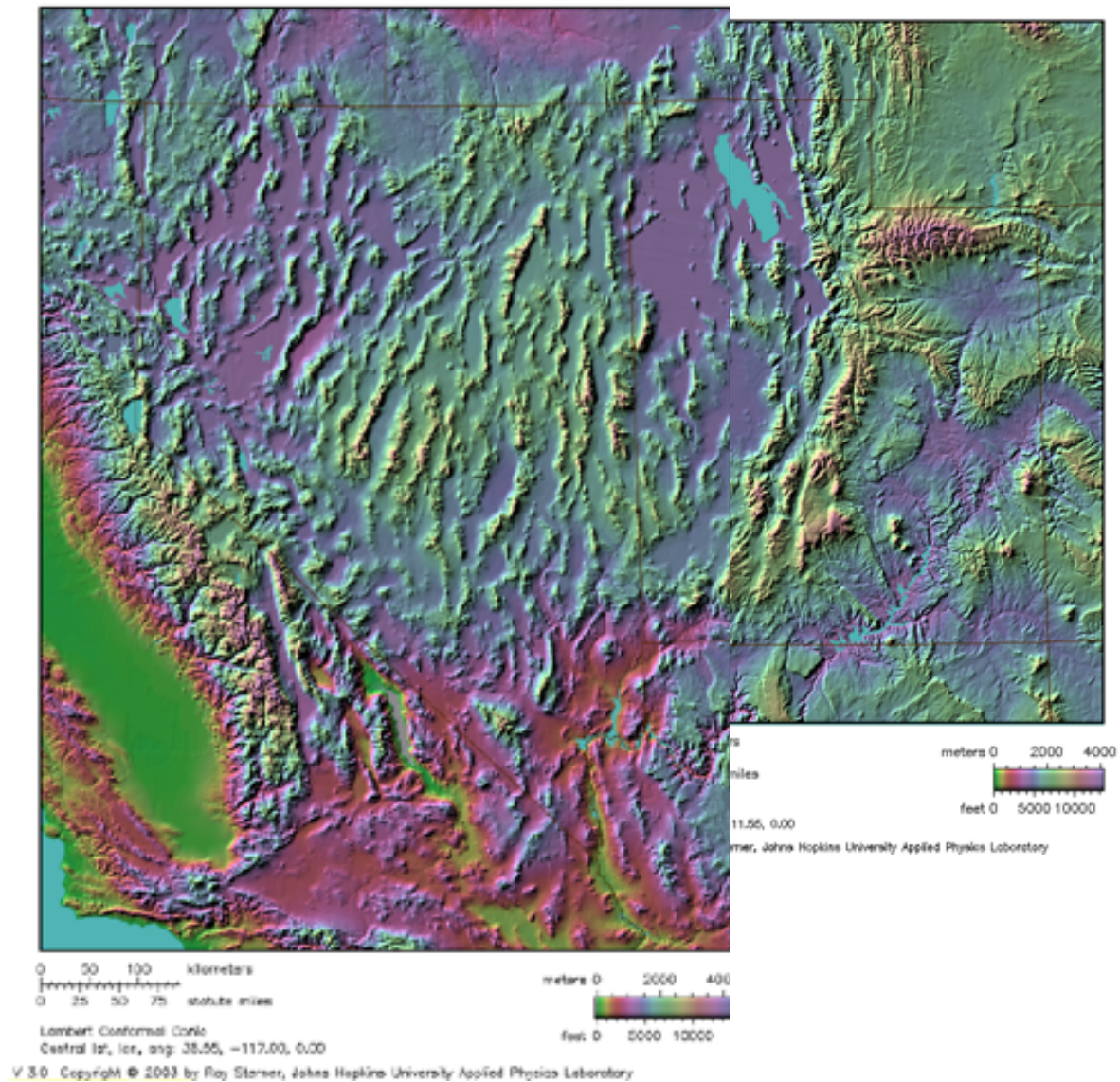
Post-Landers Maximum Strain Rate and Earthquakes of M>5.0 1950-2000



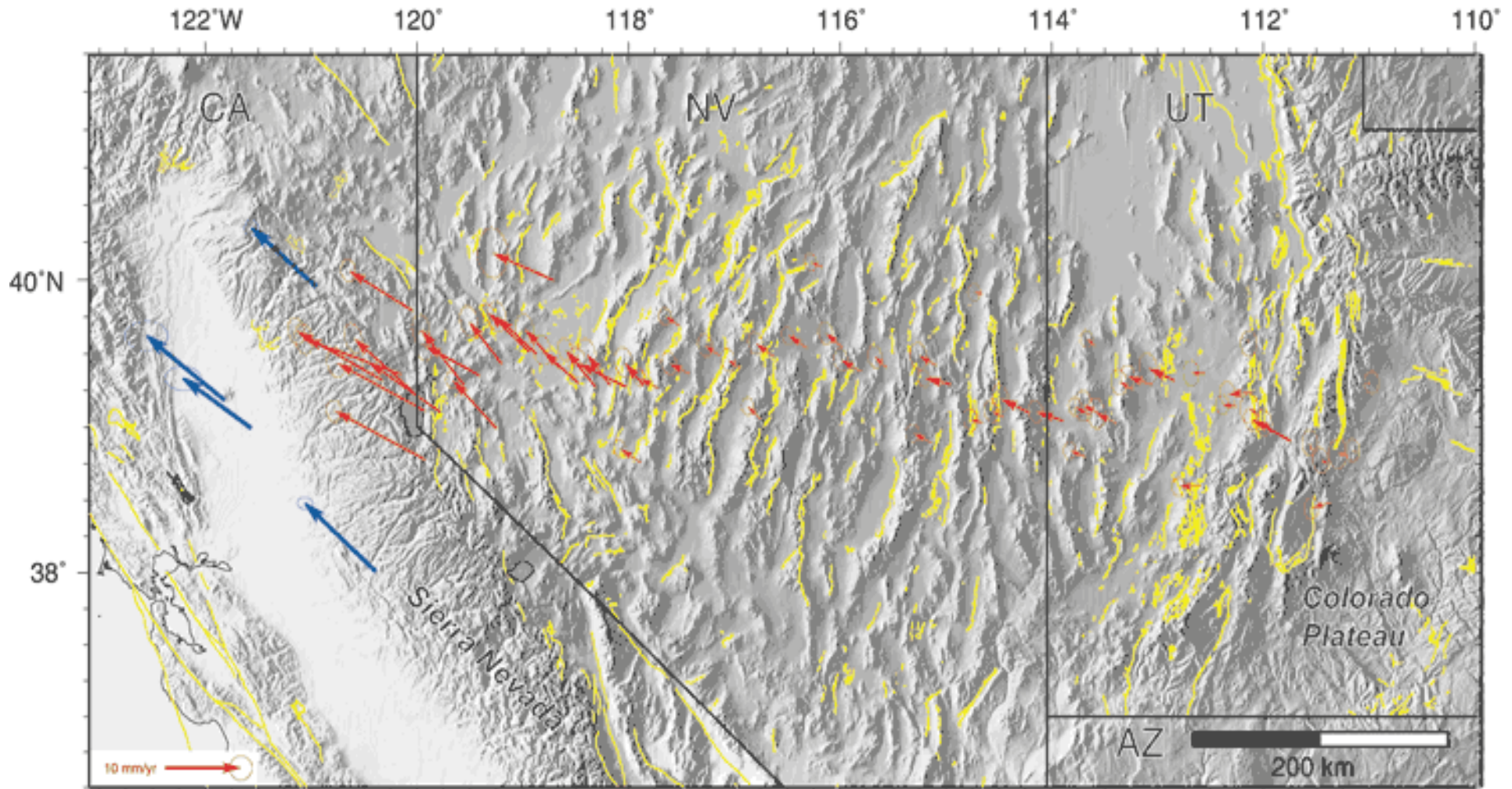
Strain Rate vs Earthquake Count (M>5.0)



Basin and Range



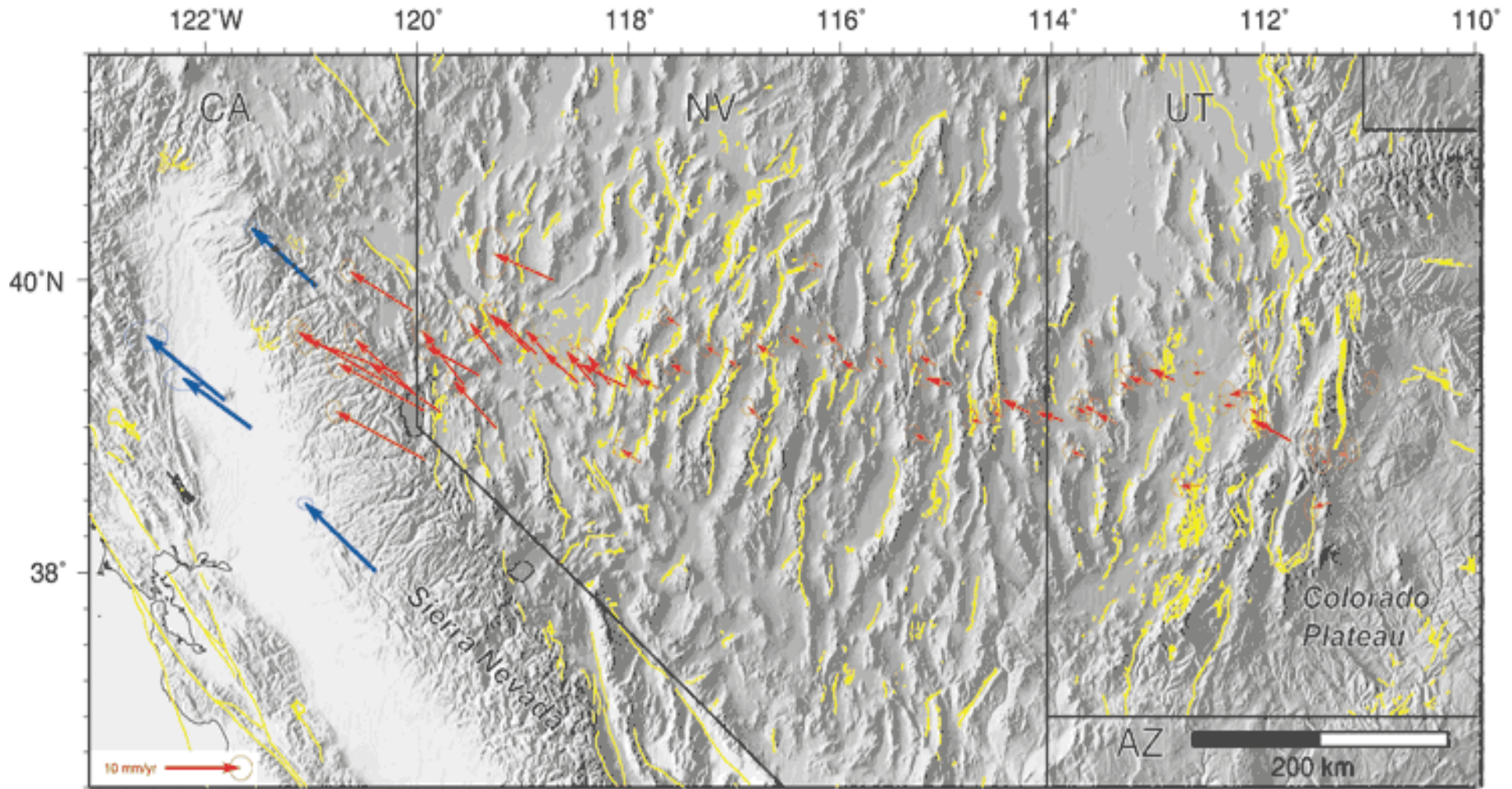
Basin and Range Velocities



Main Features: Basin and Range

- Pure extension in eastern half of B&R
 - Slow distributed extension
 - Zones of concentrated extension
- Mix of extension and strike-slip motion in western part of B&R
 - Central Nevada Seismic Belt
 - Eastern California Shear Zone/Walker Lane
- Total motion across Basin and Range reaches 10 mm/yr

Basin and Range Velocities



Discrete High-Strain Shear Zones

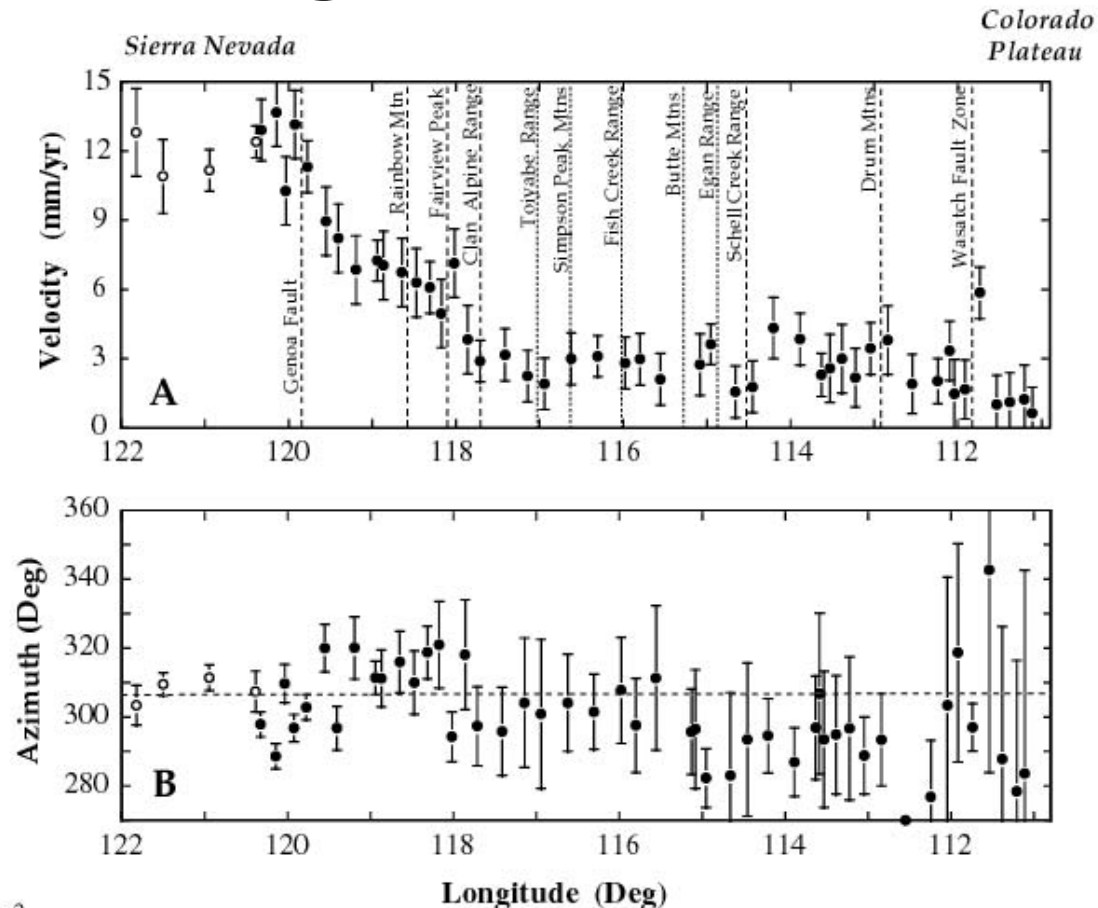
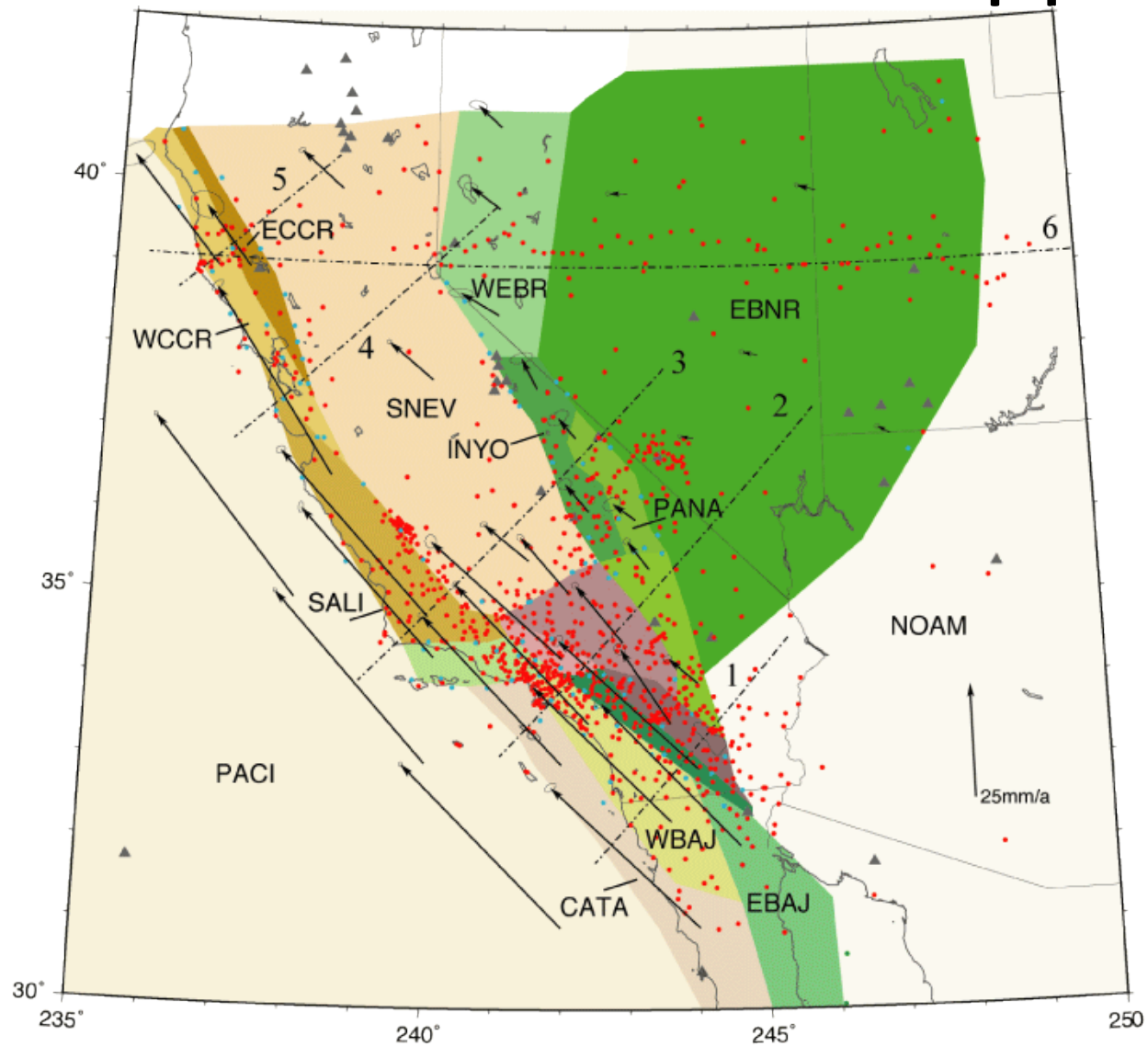


Fig. 2

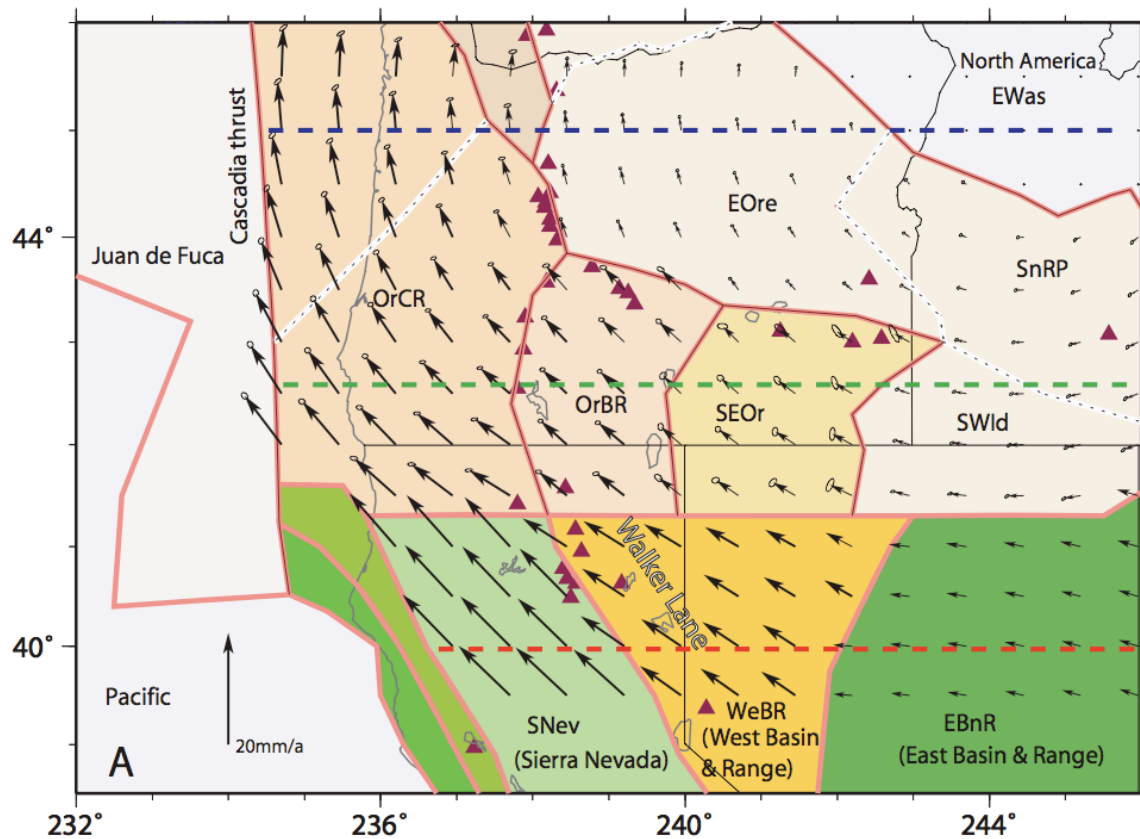
- Broad deforming zone consists of a few discrete high-strain shear zones separated by regions of low strain (*Thatcher et al., 1999*).

Leads to a Block Model Approach

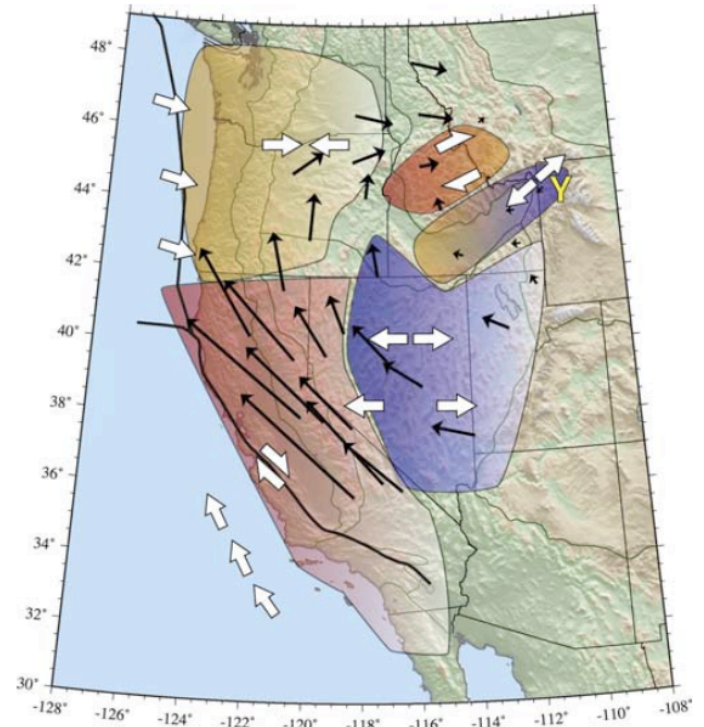


Rob McCaffrey, 2003, Fall AGU

Block Models for the Lower 48

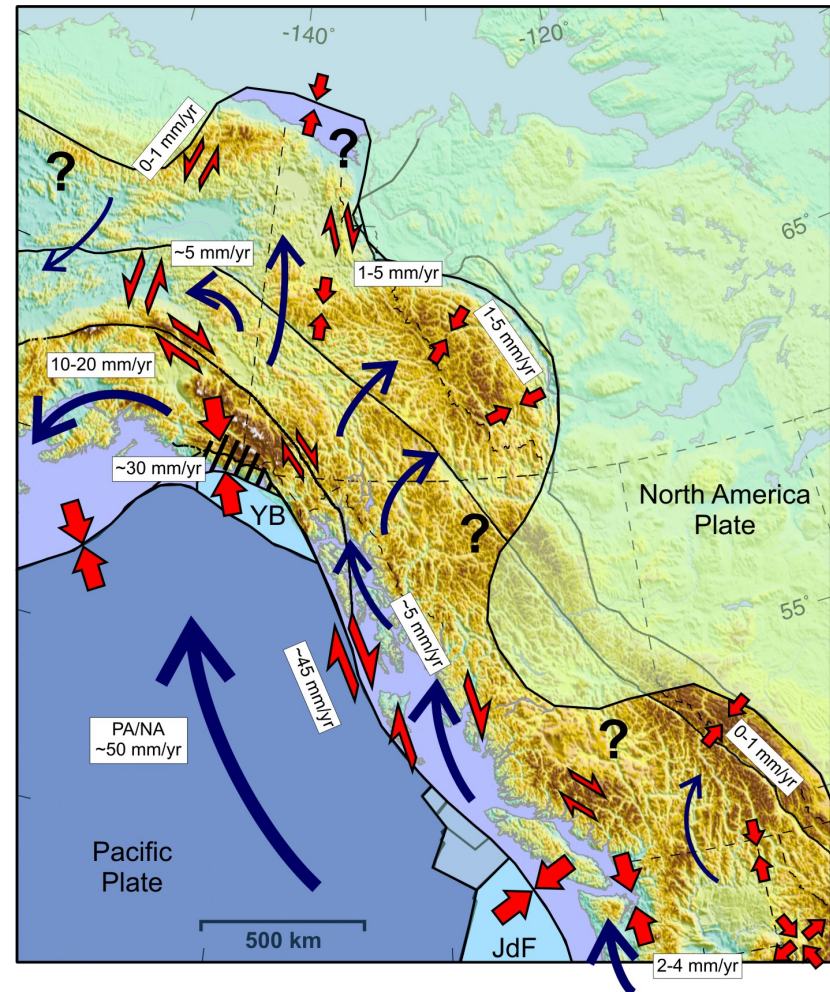
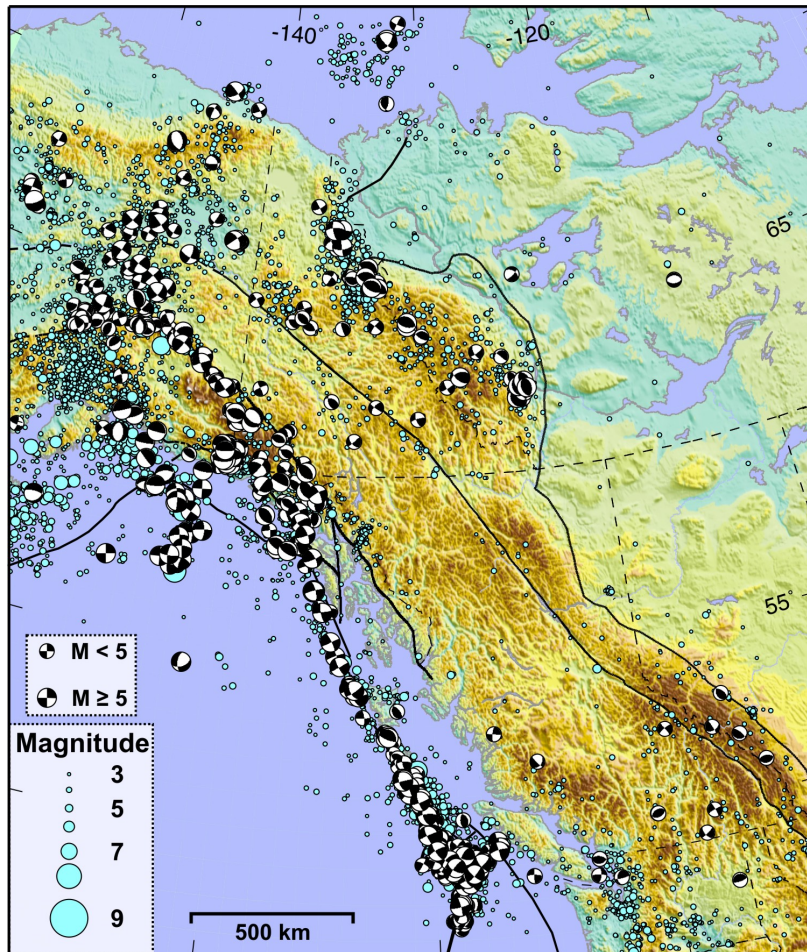


McCaffrey et al. (2007)



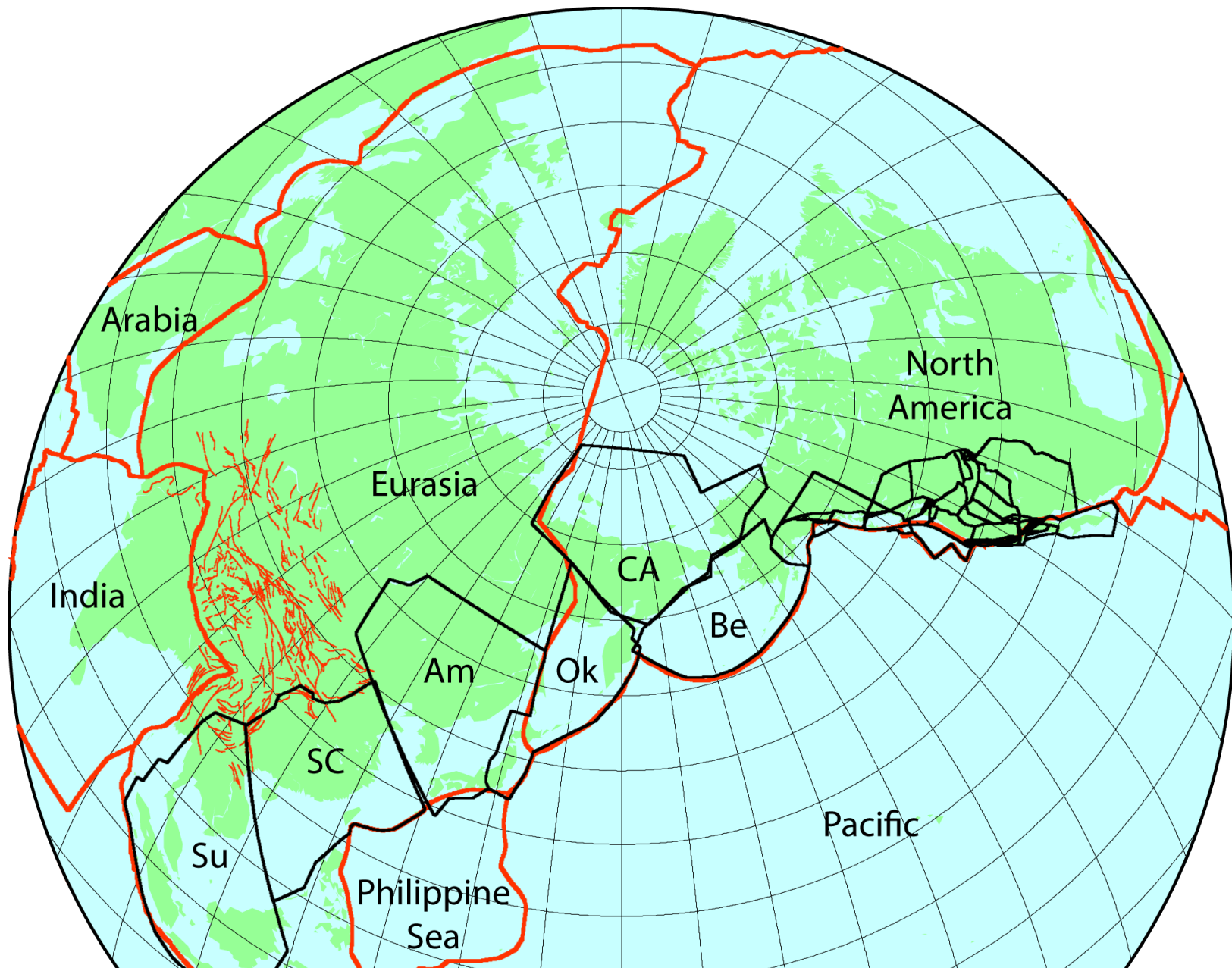
Puskas and Smith (2009)

Northern Cordillera

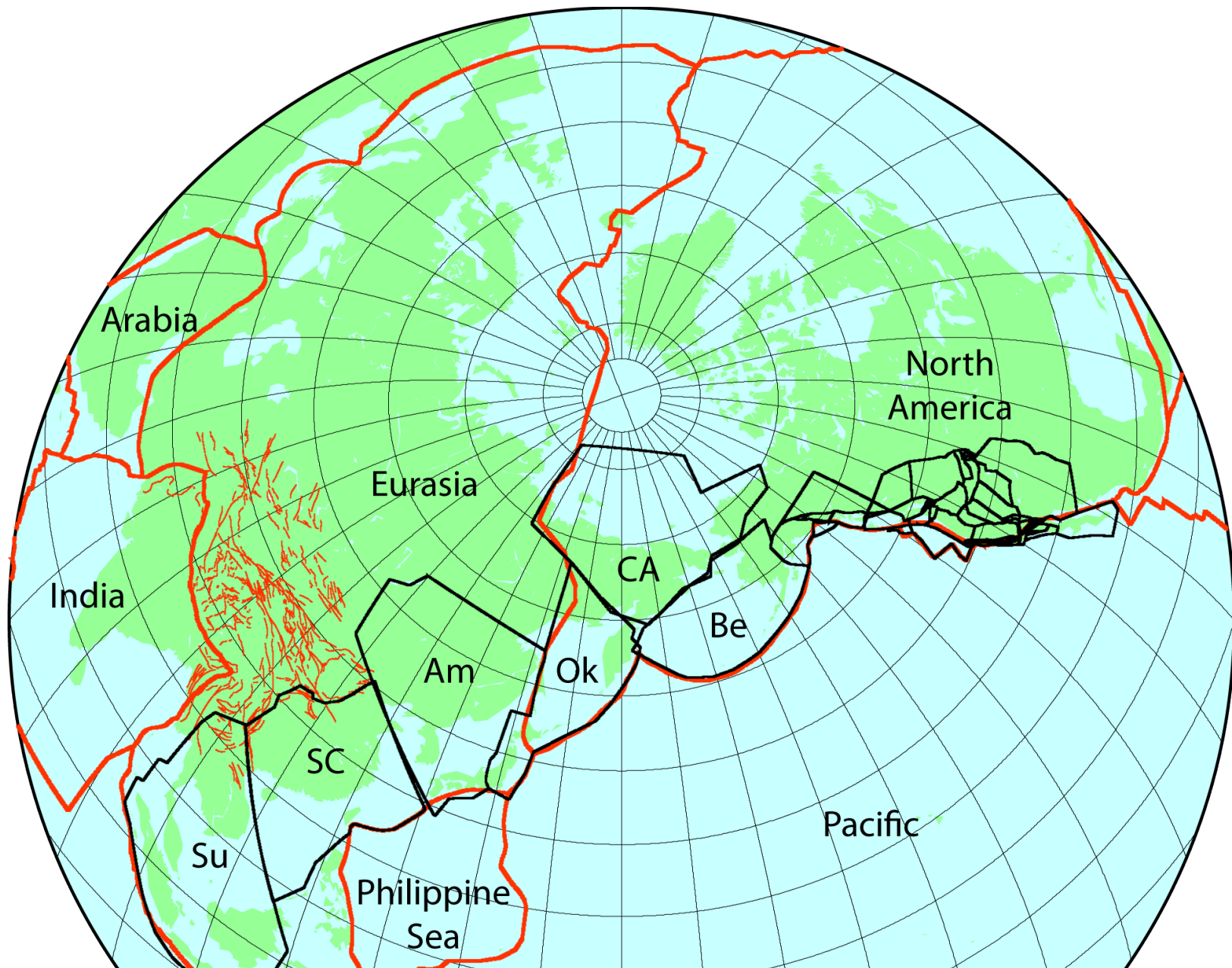


Mazzotti et al., 2008

Blocks Around the North Pacific

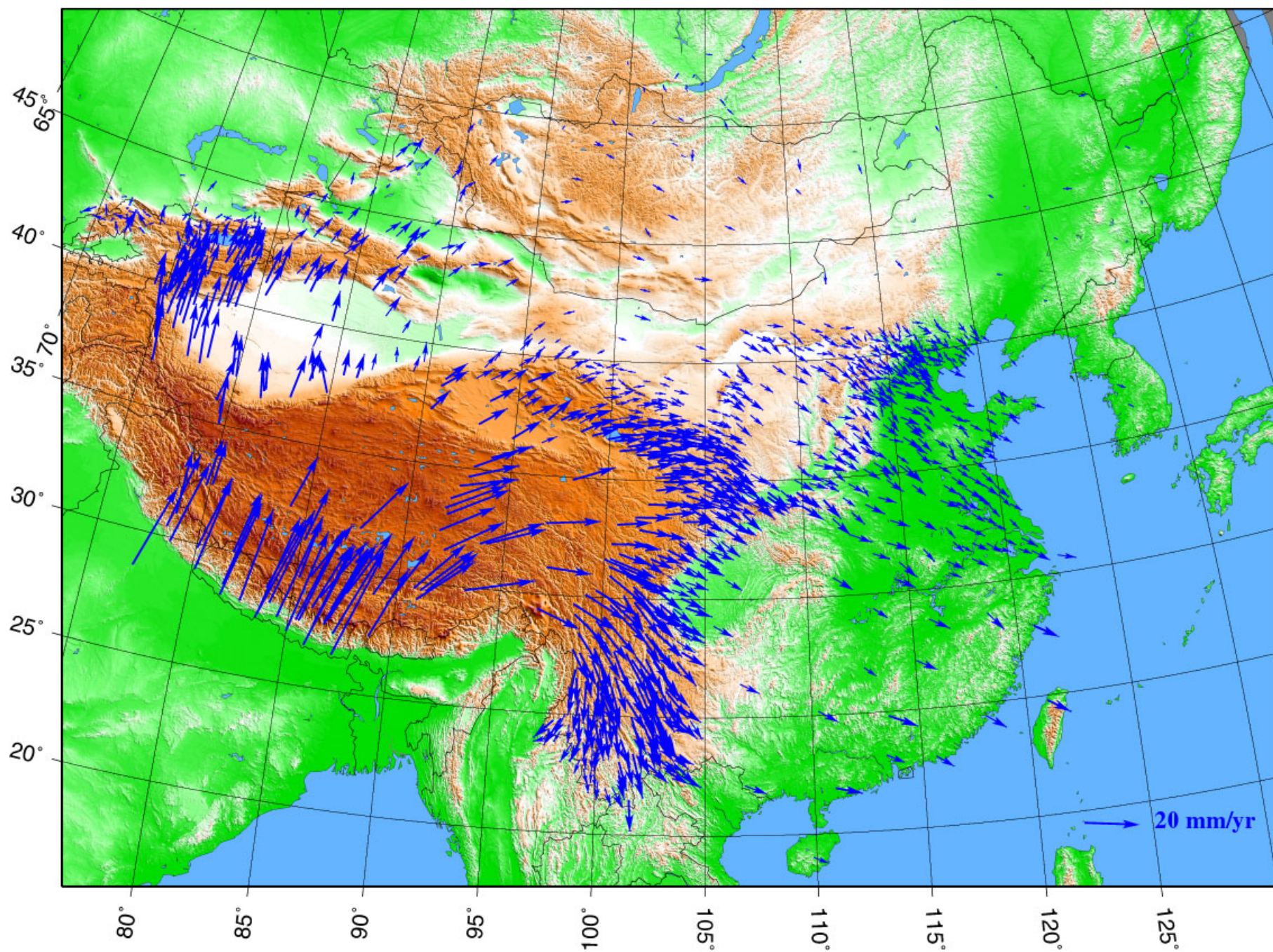


Blocks Around the North Pacific

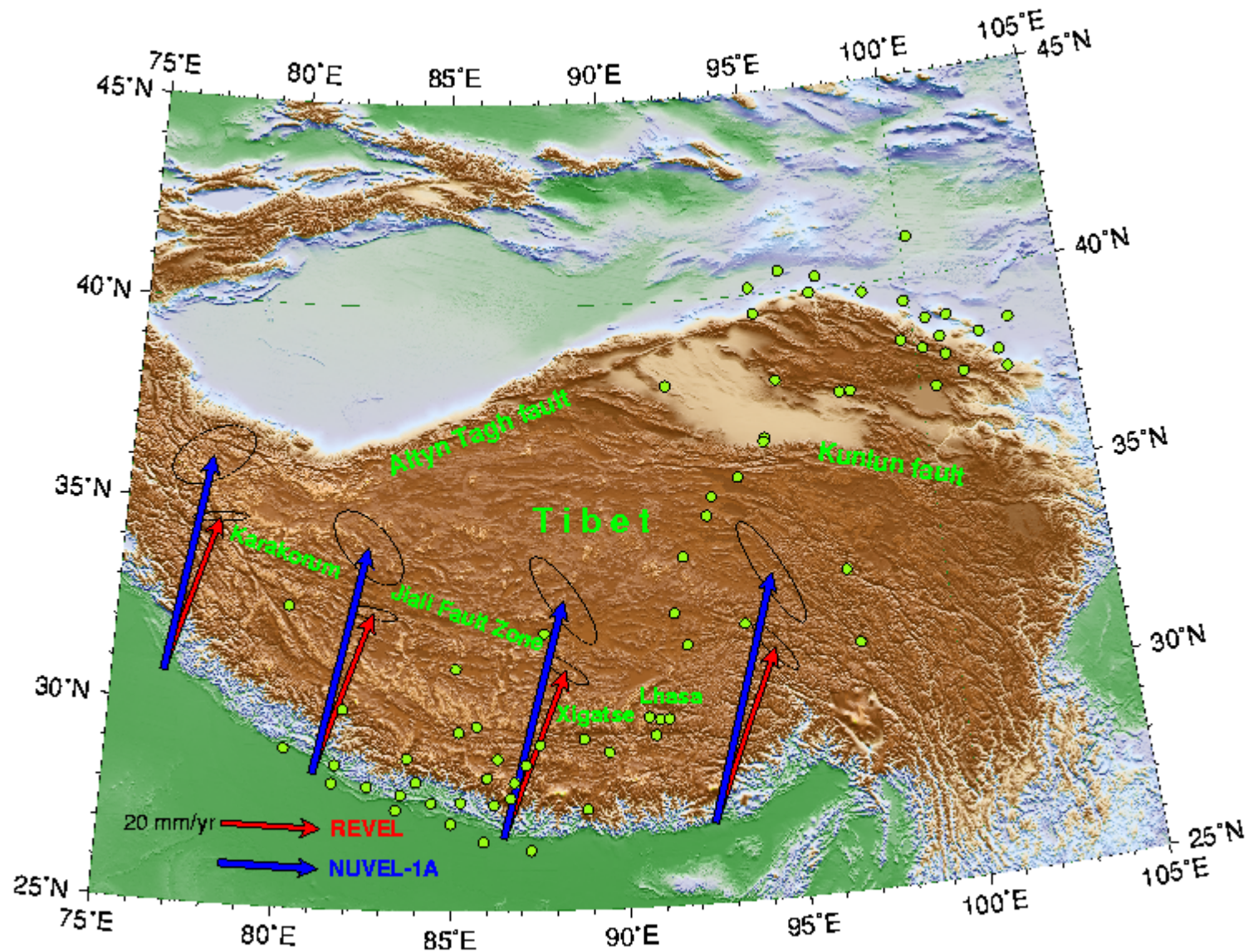


A Decade of GPS in China and Tibet

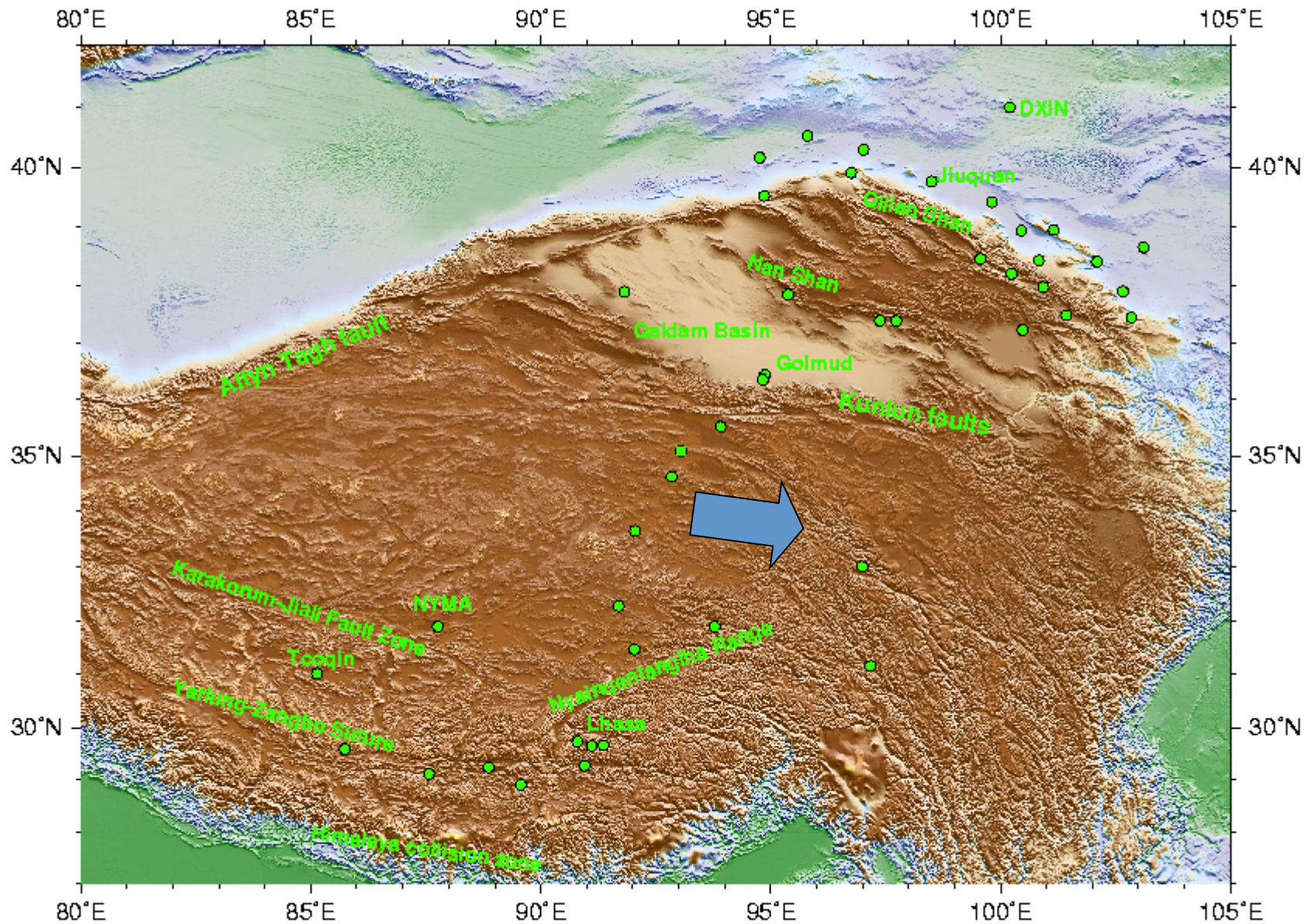
- First GPS survey in Tibet and Nepal in 1991
- Chinese agencies began surveys in 1992
- Built collaborative relationships with Chinese agencies
- Current China – Alaska – Colorado collaboration began in 1995 with goals of:
 - Measure convergence across Himalaya
 - Measure extension across southern Tibet
 - Investigate large-scale tectonic models for India-Eurasia collision



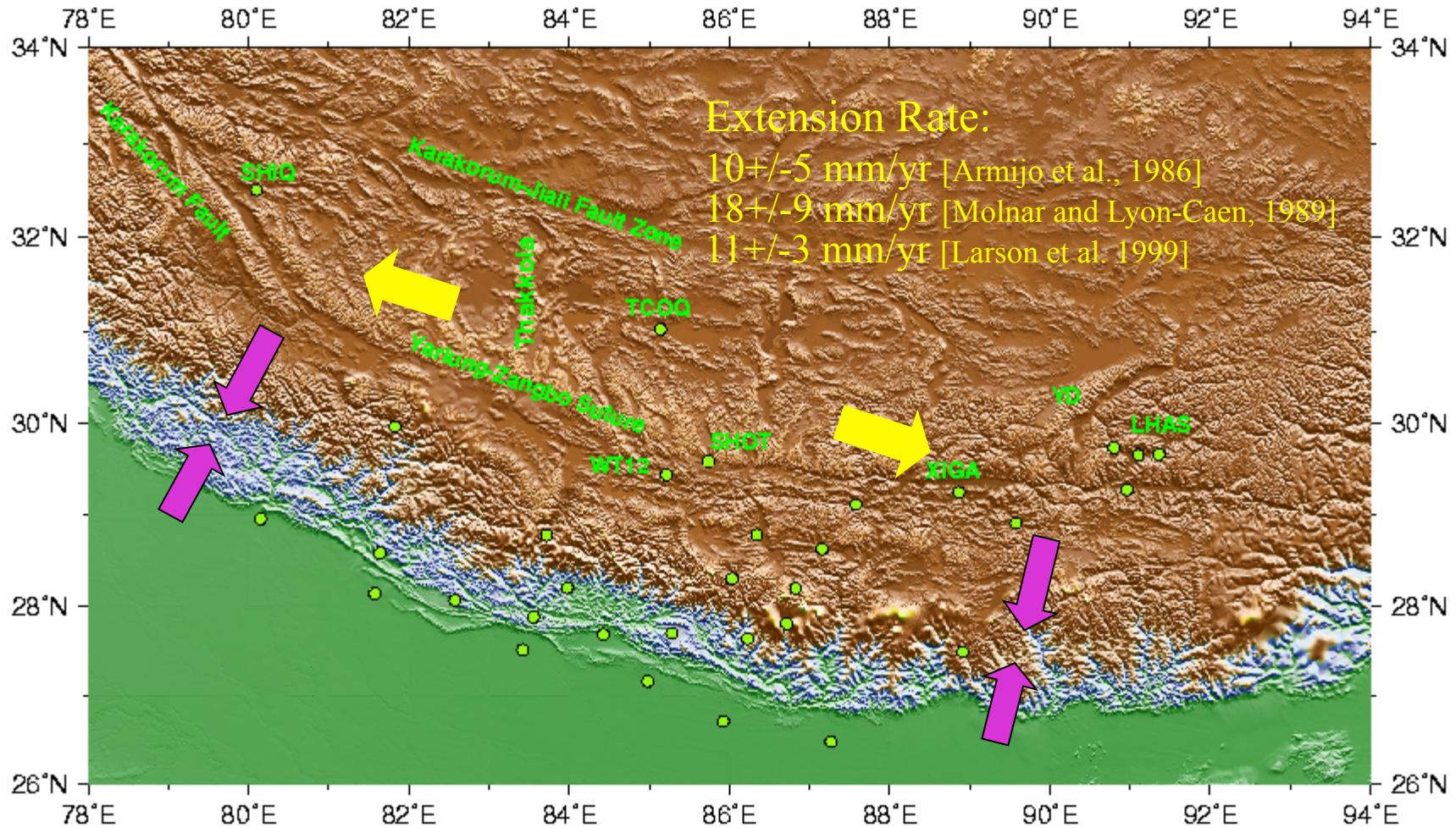
Relative Plate Motions



Tectonic Setting



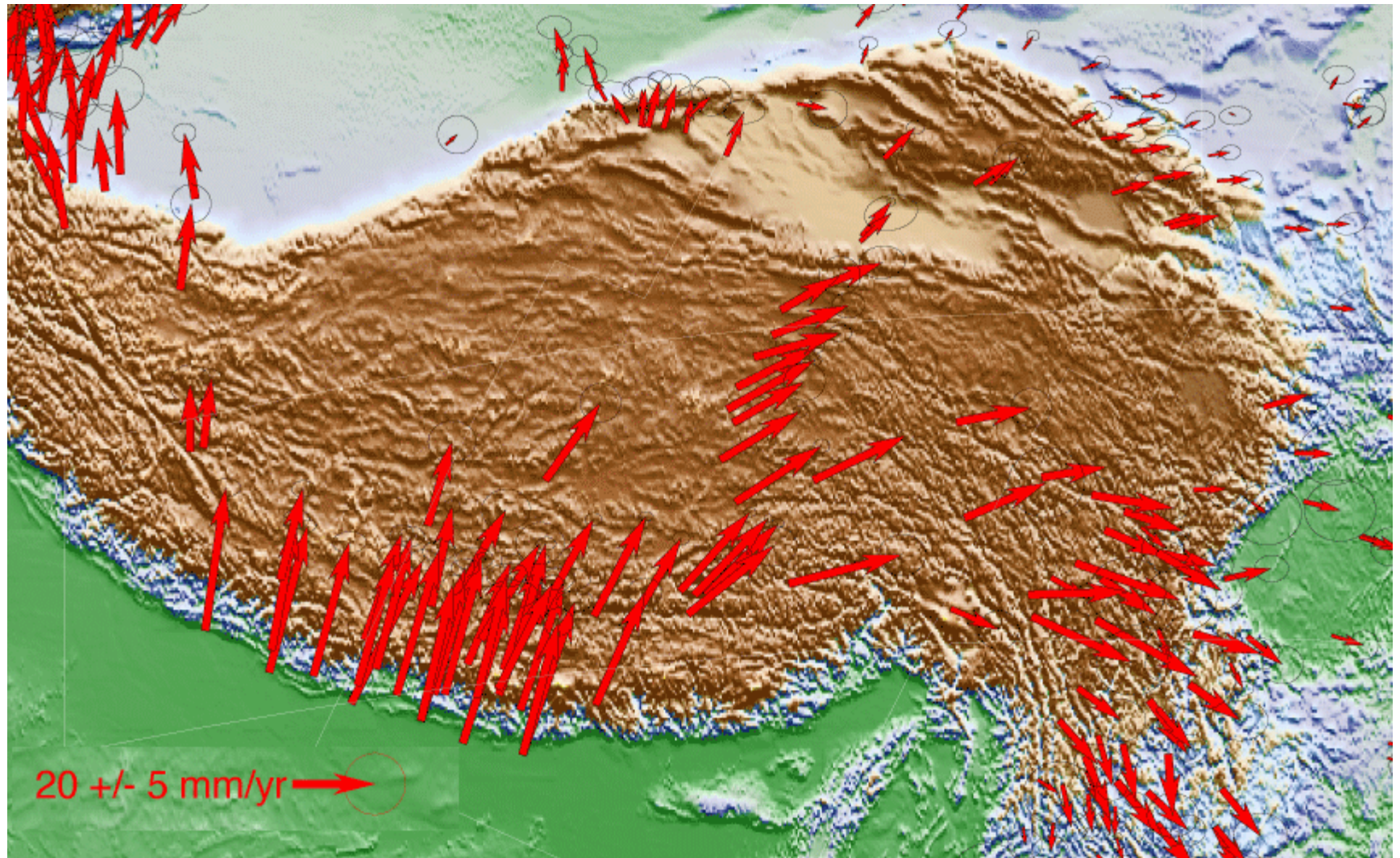
Tectonic Setting



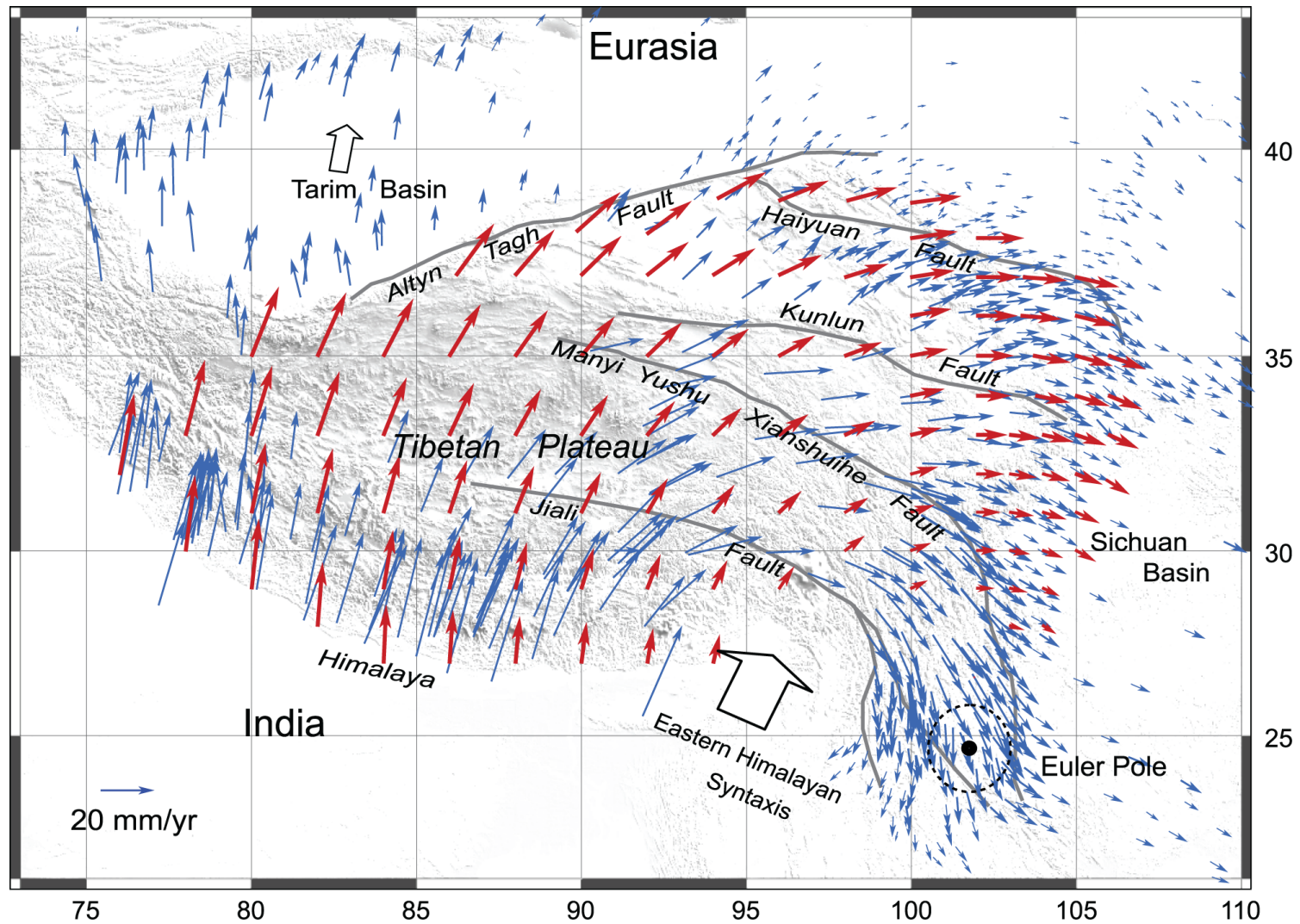
Convergence Rate:

- 10-25 mm/yr [Molnar and Deng, 1984; Molnar, 1987]
- 18 \pm 7 mm/yr [Molnar and Lyon-Caen, 1989]
- ~18 mm/yr [Larson et al., 1999; Bilham et al, 1997]

Tibet Velocities

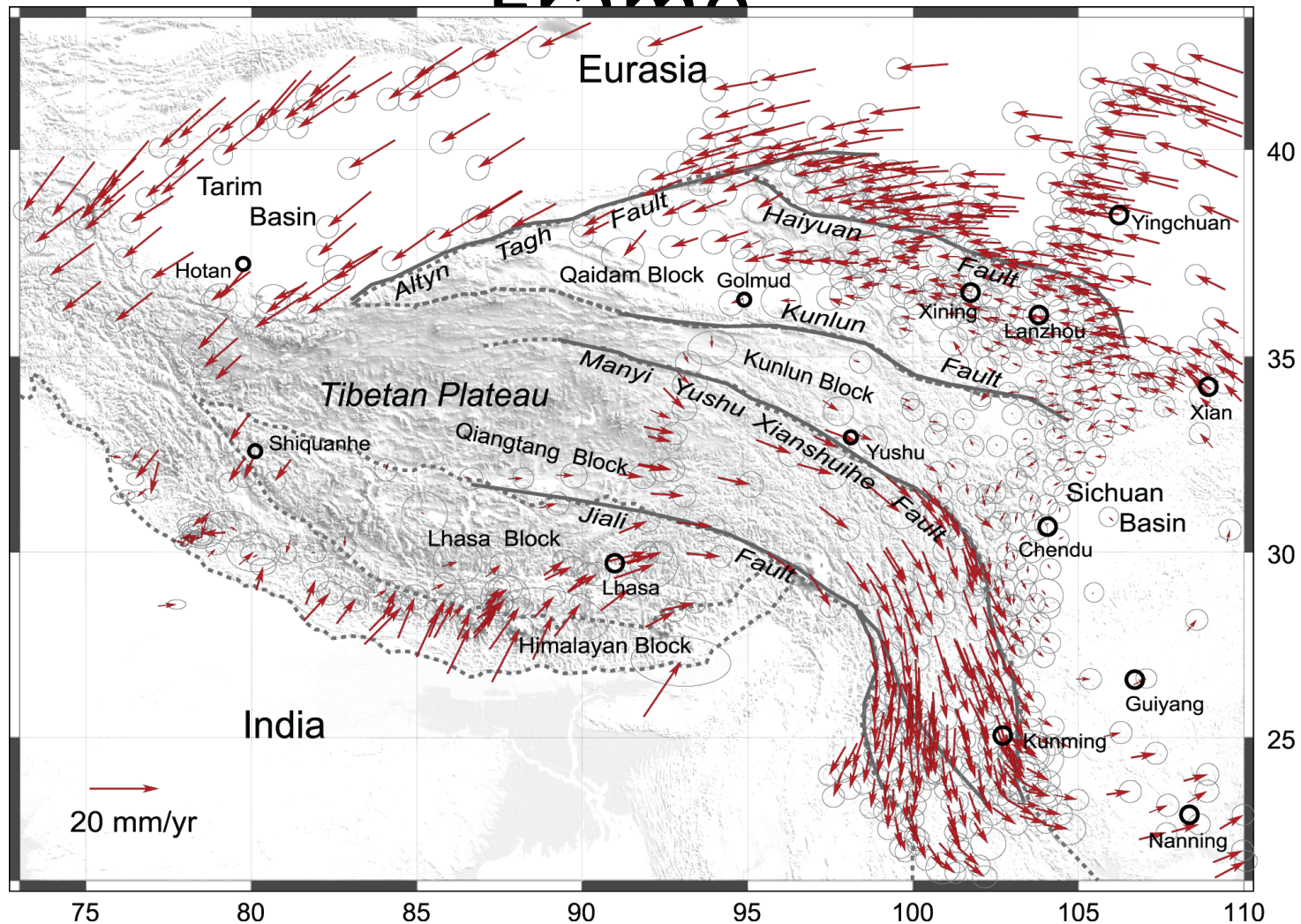


Latest Published Velocity Field



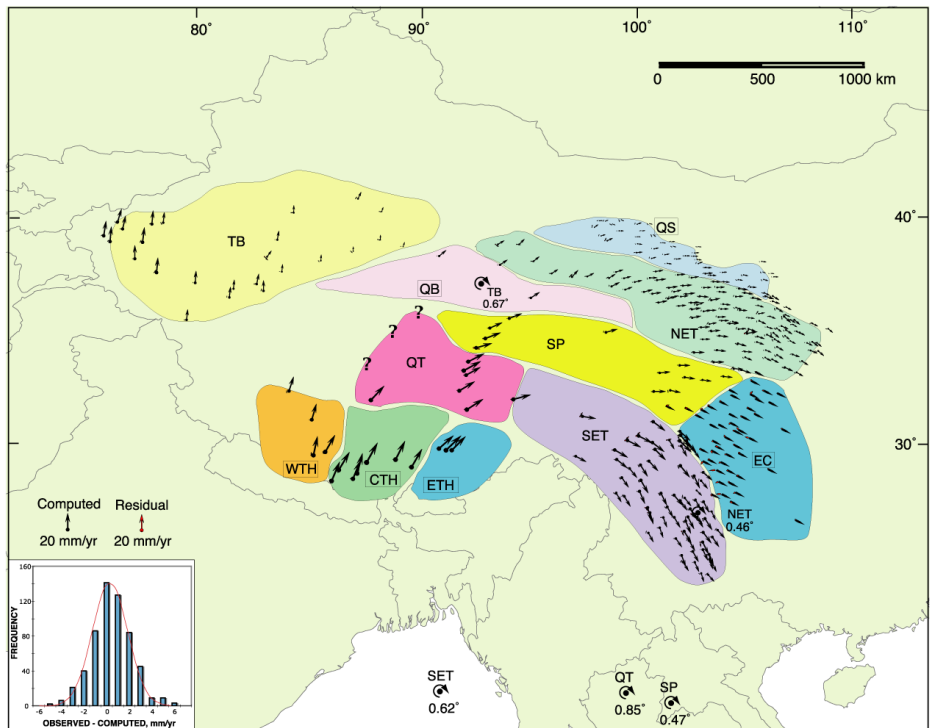
Gan et al. (2007 JGR)

“Tibetan Plateau Reference Frame”

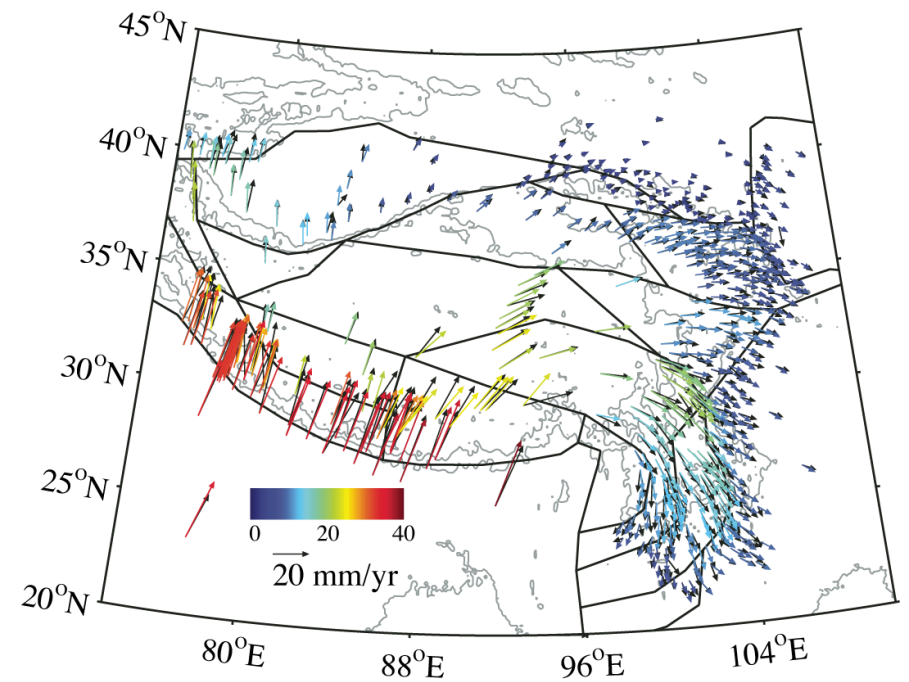


Gan et al. (2007) explained these motions in terms of a series of blocks separated by mostly strike-slip faults → plateau is deforming, but not changing area.

Thatcher vs. Meade

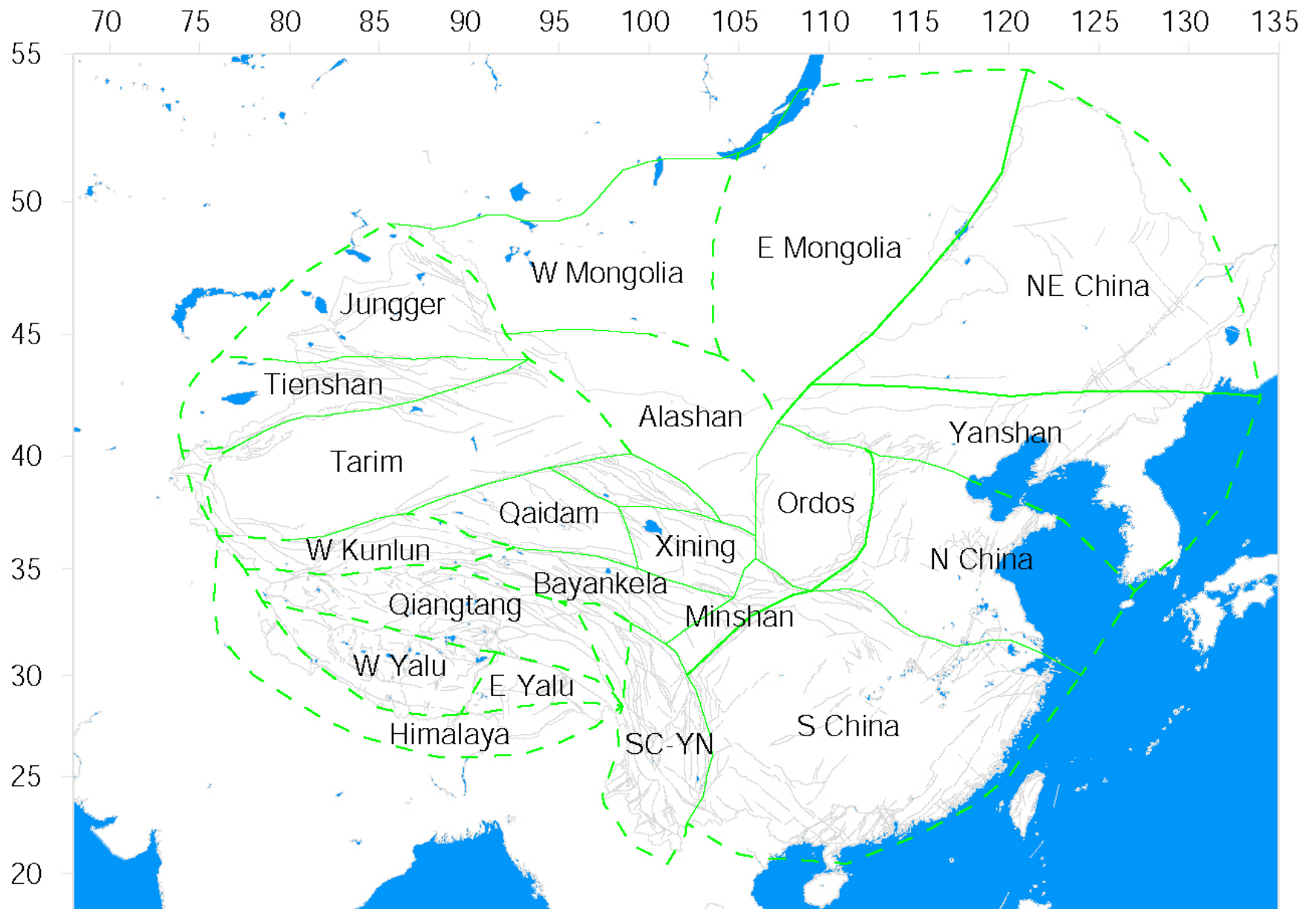


Thatcher, 2007

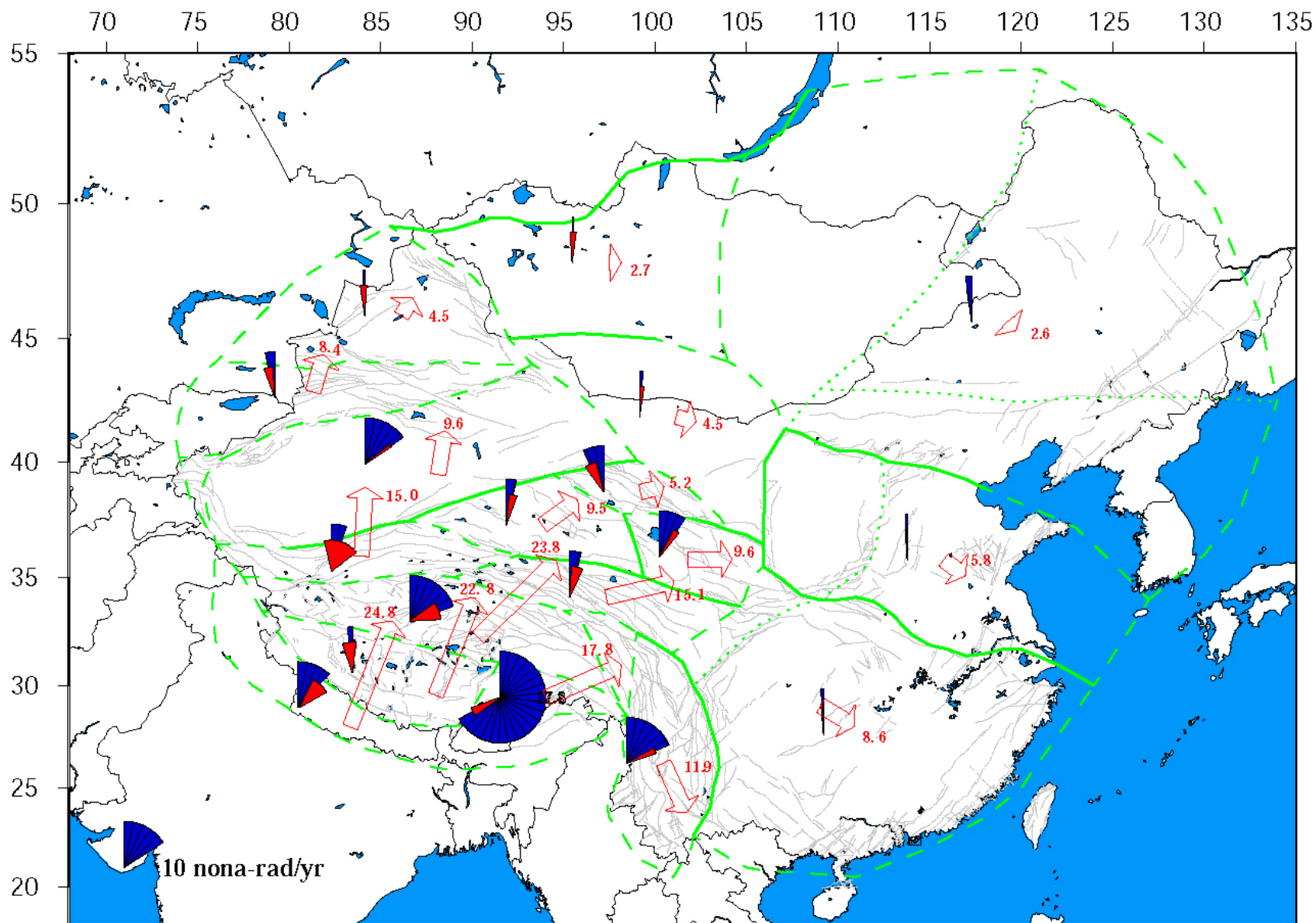


Meade, 2007

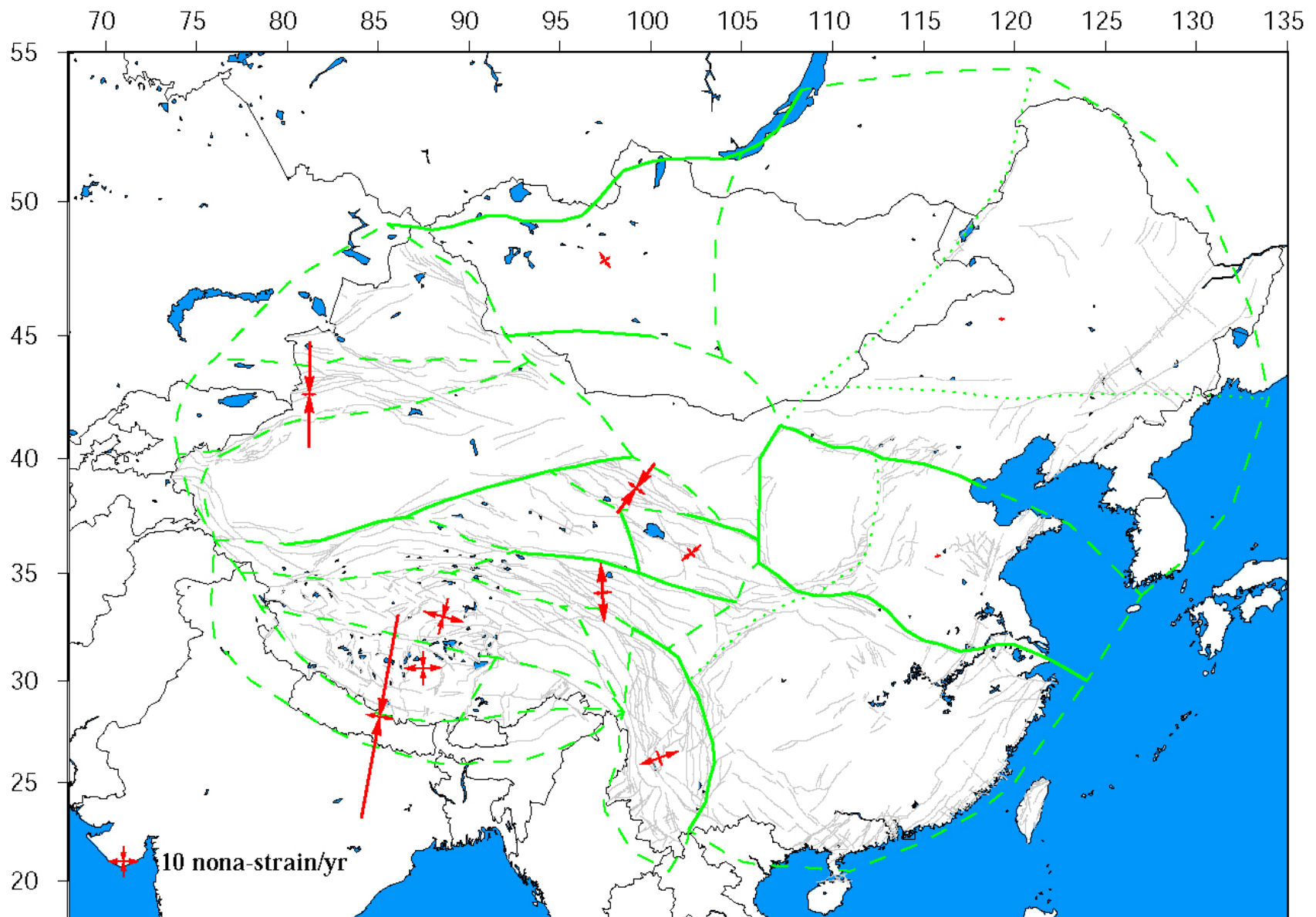
Starting Block Motion Model



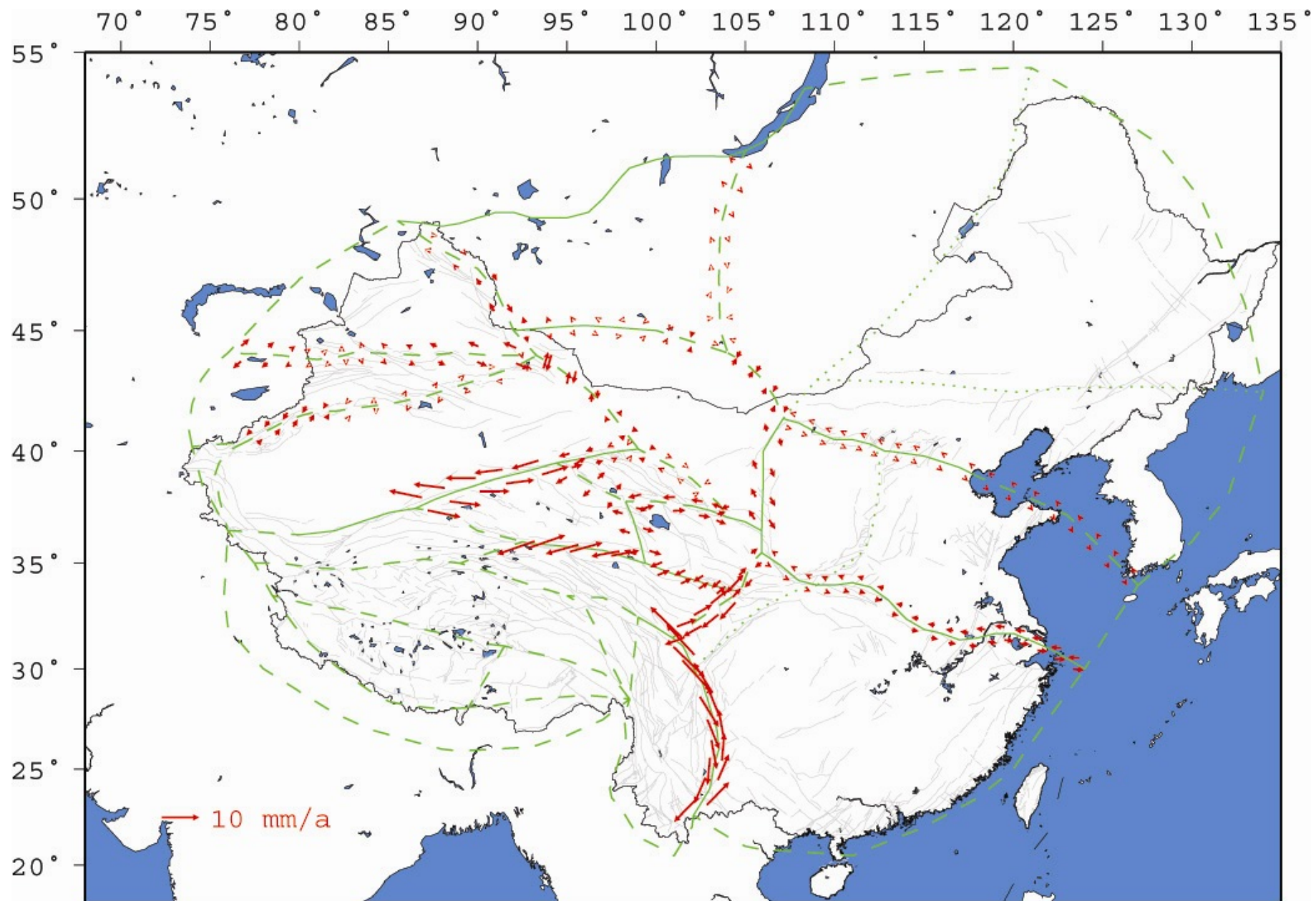
Block motion velocities and rotation rates

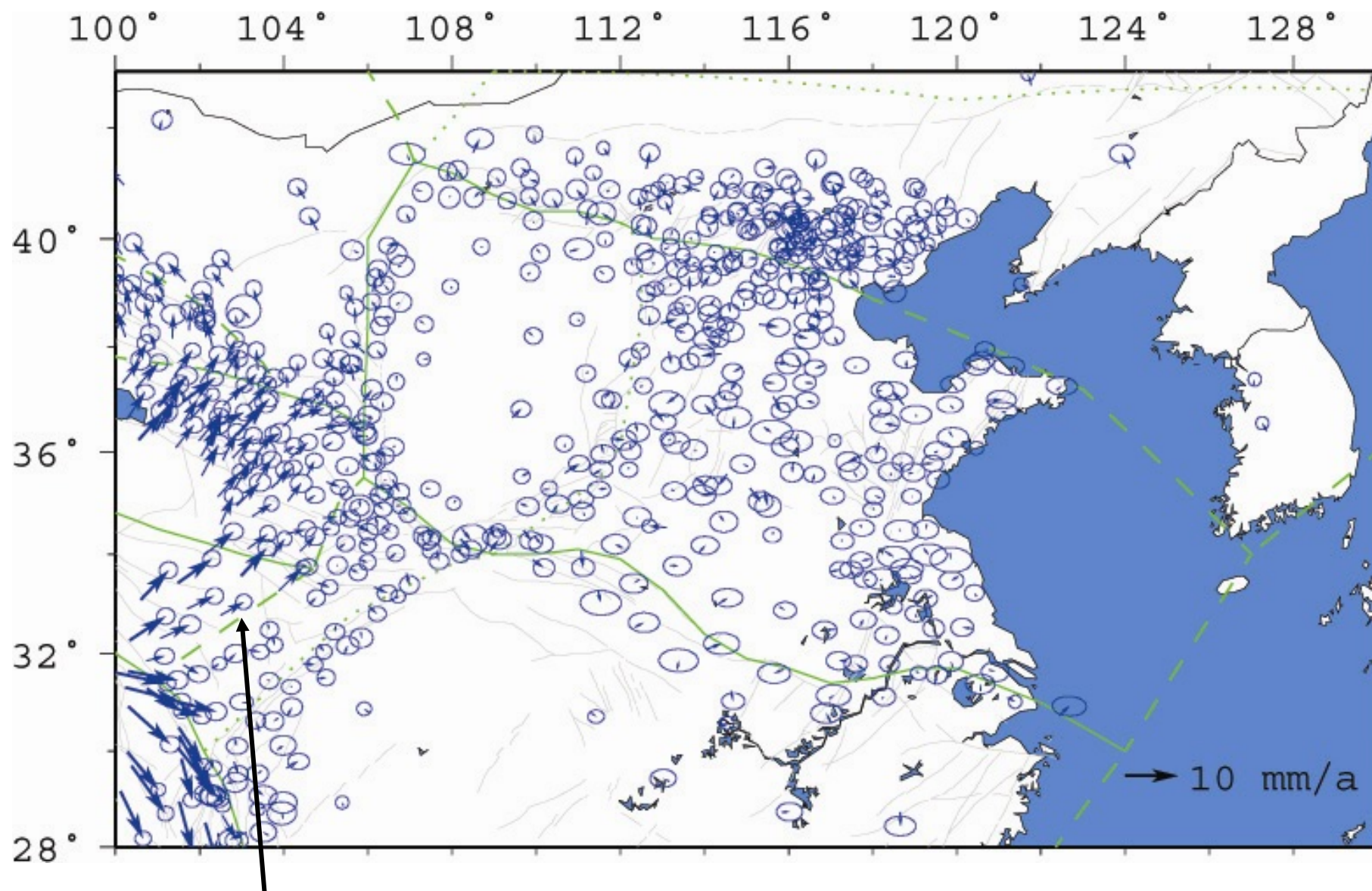


Block internal principal strain rates

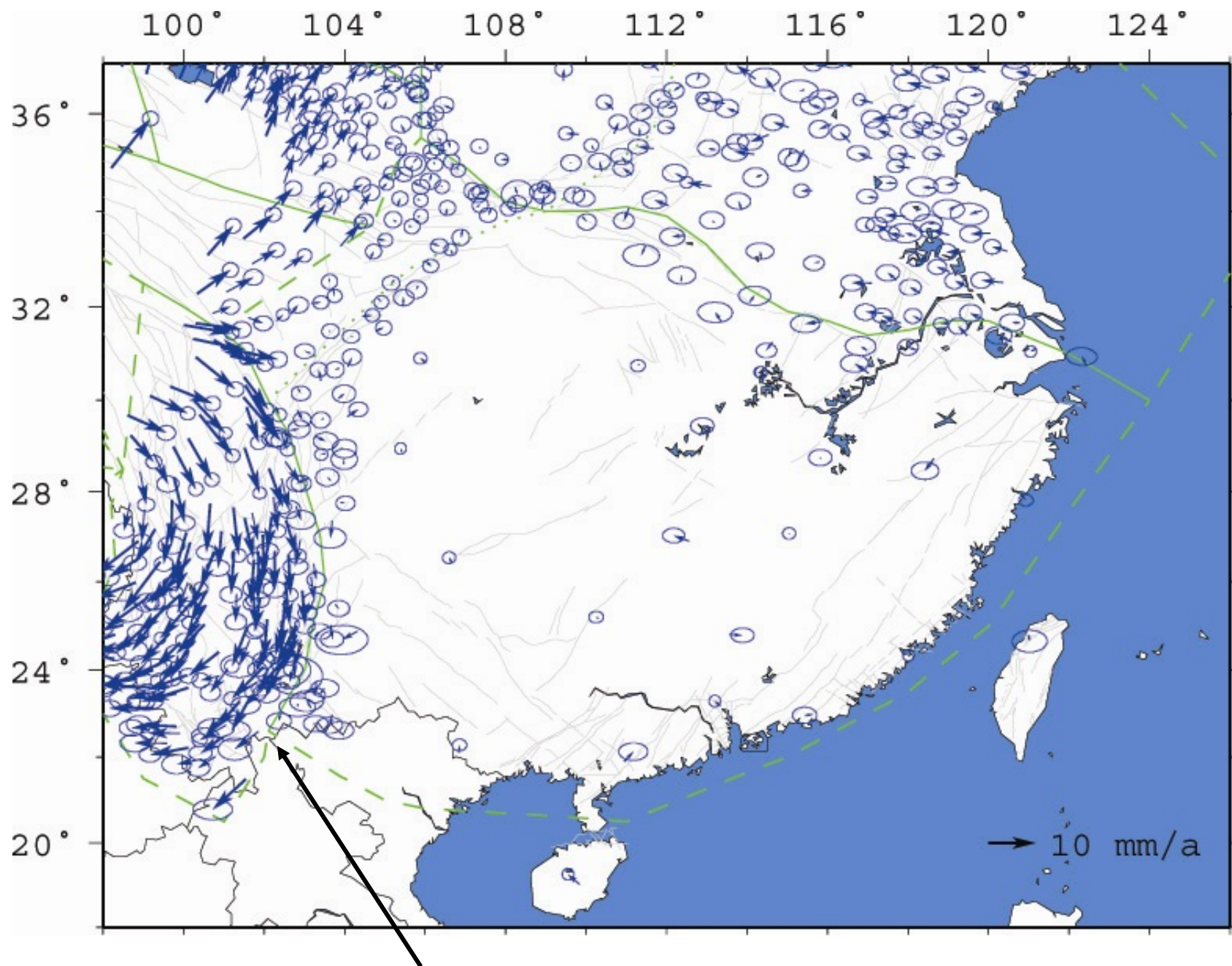


Relative Motion (Fault Slip) Rates at Block Boundaries



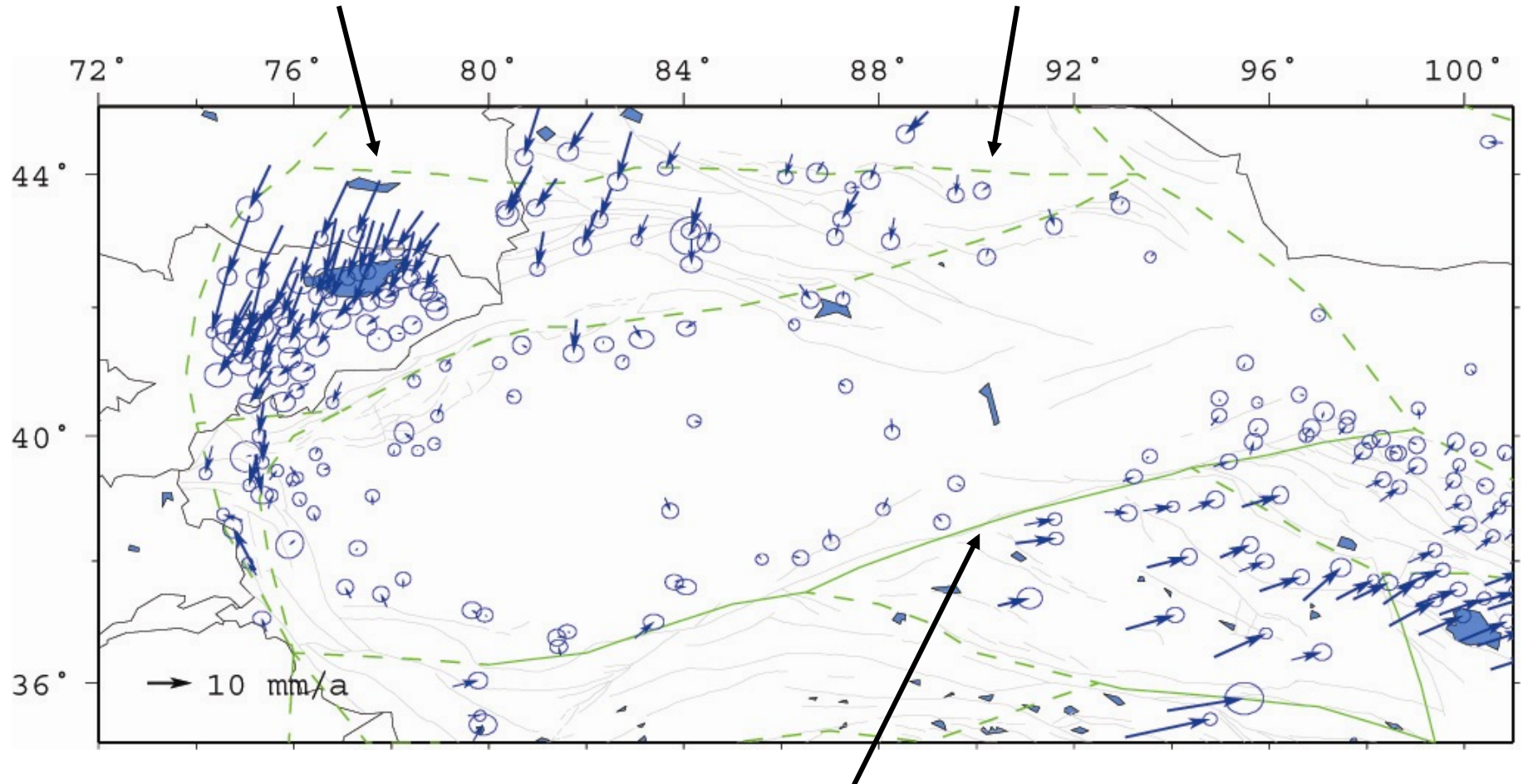


4-5 mm/yr right slip along a previously unknown fault zone



8-10 mm/yr left slip along Xianshuihe-Xiaojiang fault system, extending southwestward across Red River fault

Progressive westward increase of north-south convergence across Tien Shan range



Slow (~6 mm/yr) left slip along central Altyn Tagh fault

Complications (1)

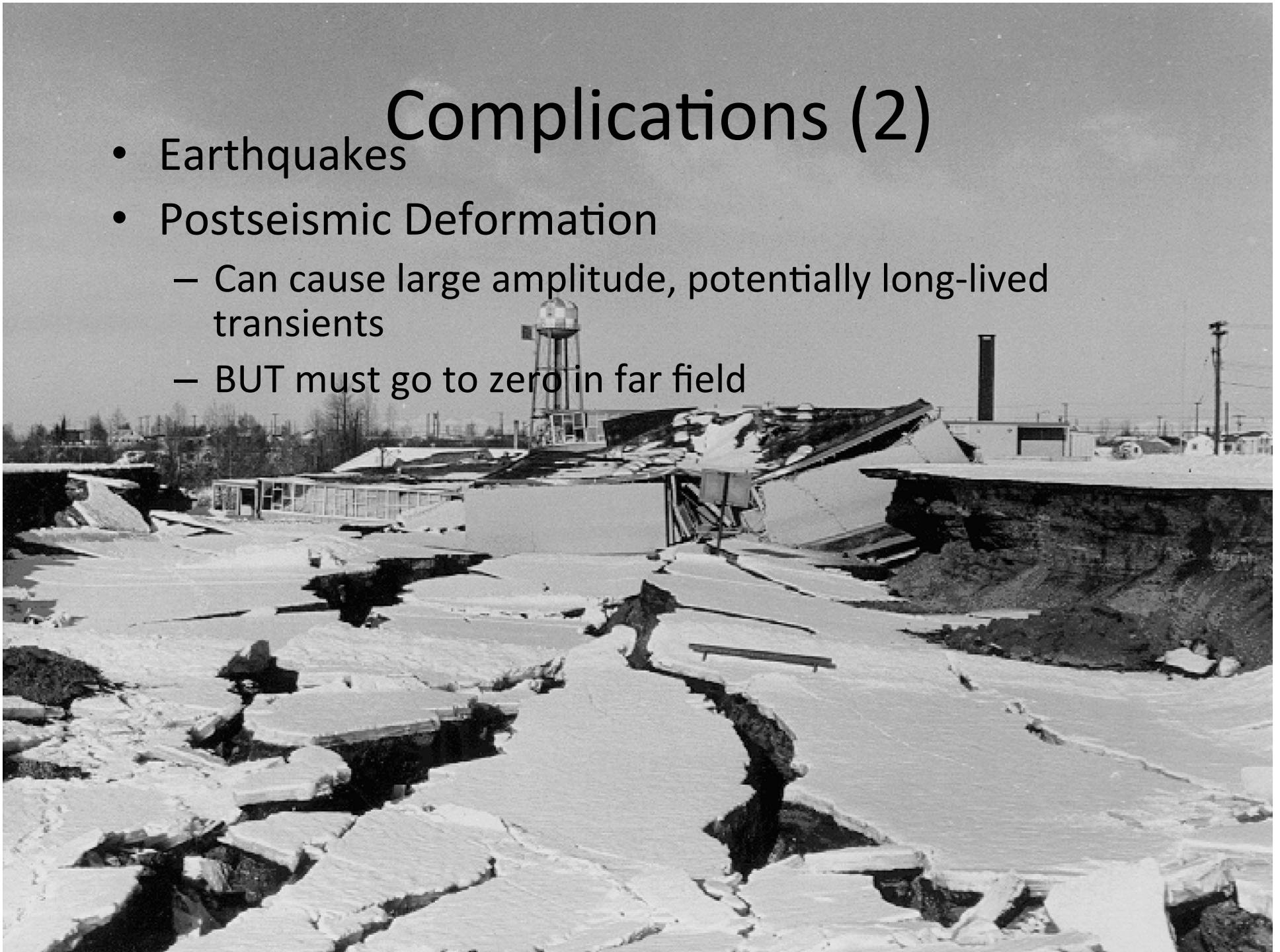
All of the work shown here assumes short-term velocity equals long-term velocity. It may not!
Velocities can be biased by several effects:

- Loading (seasonal and other)
 - Heki (2003) showed that the strong seasonal signals in Japanese network explainable by physical loading models
- Hydrologic effects (famous subset of SCIGN)

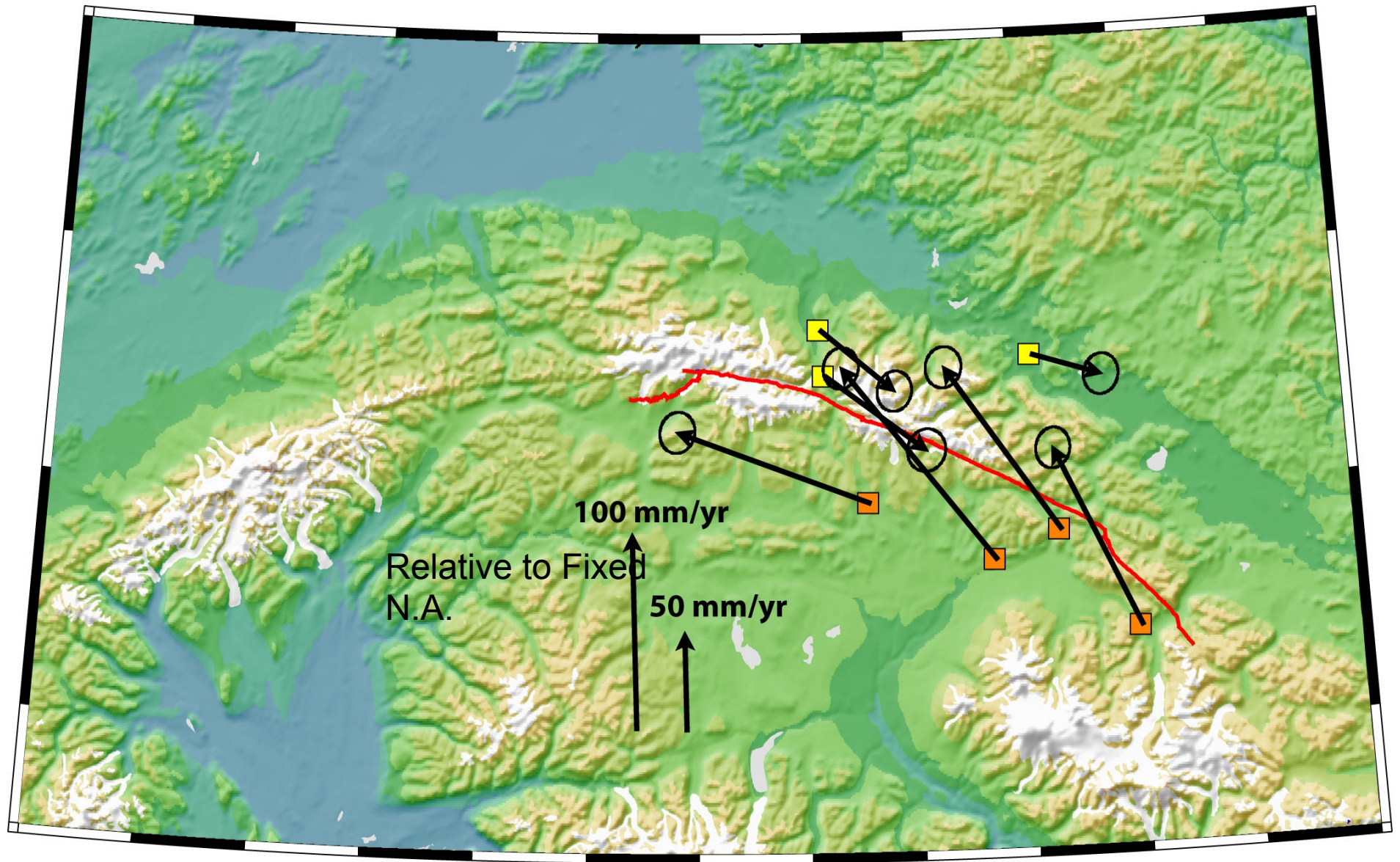


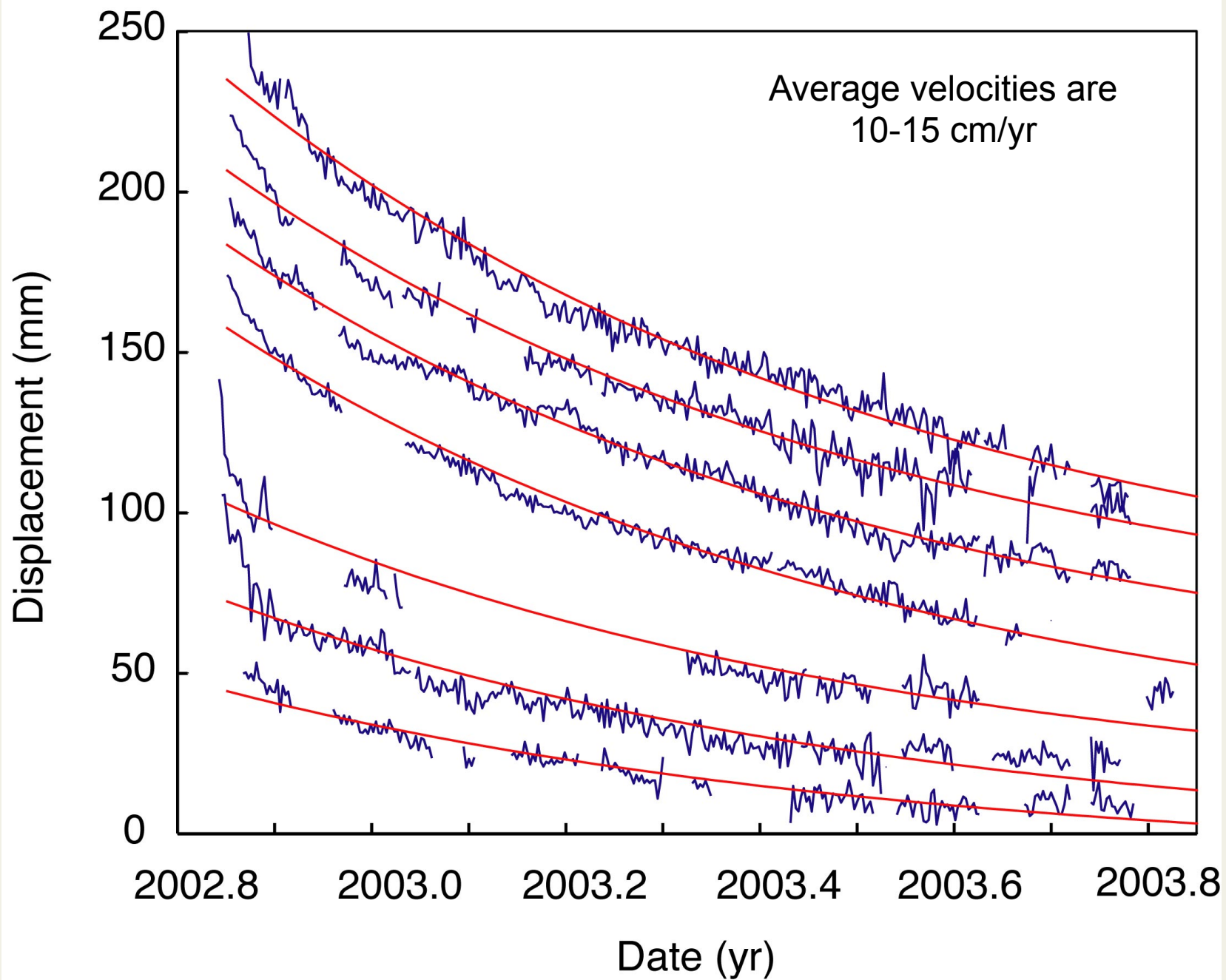
Complications (2)

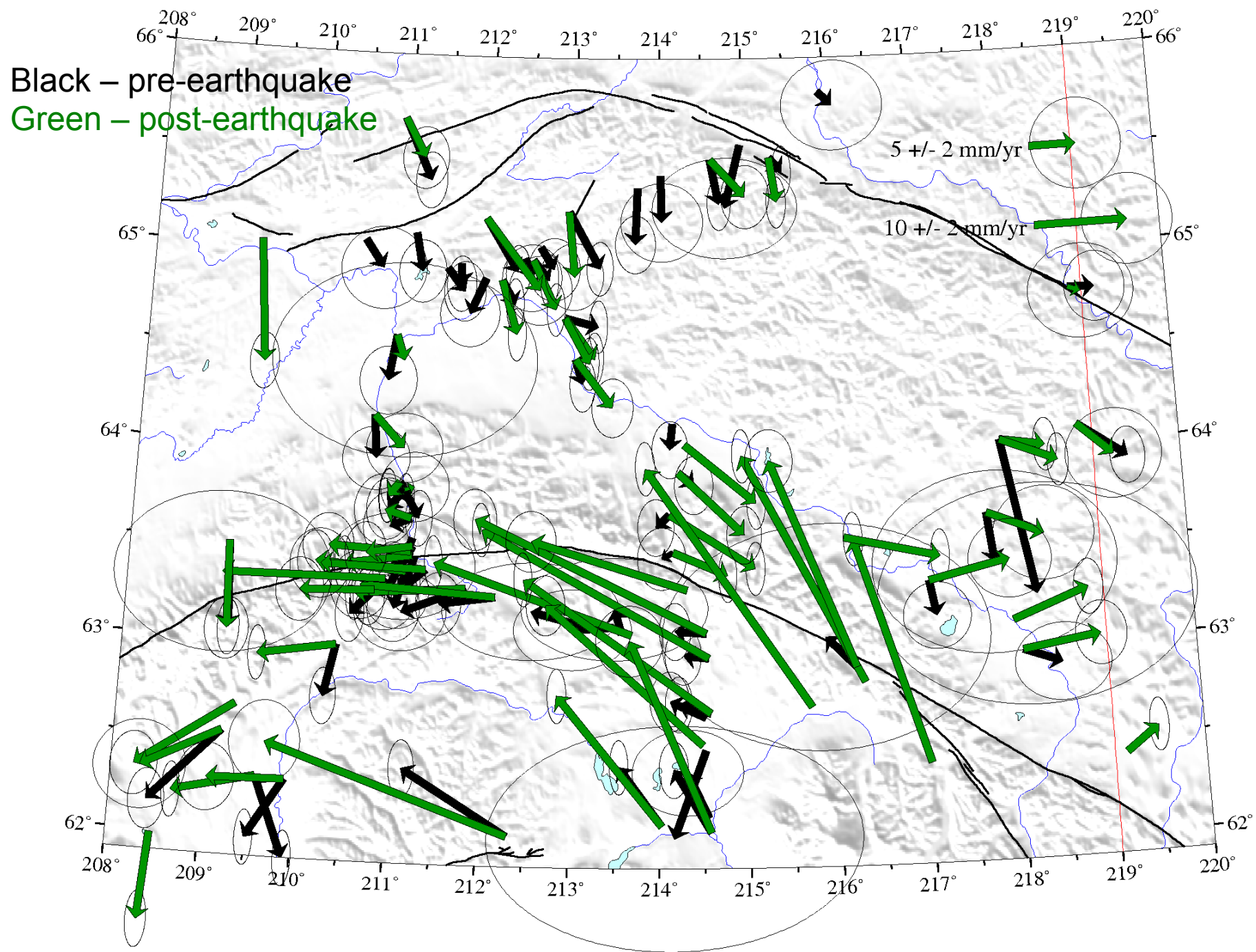
- Earthquakes
- Postseismic Deformation
 - Can cause large amplitude, potentially long-lived transients
 - BUT must go to zero in far field



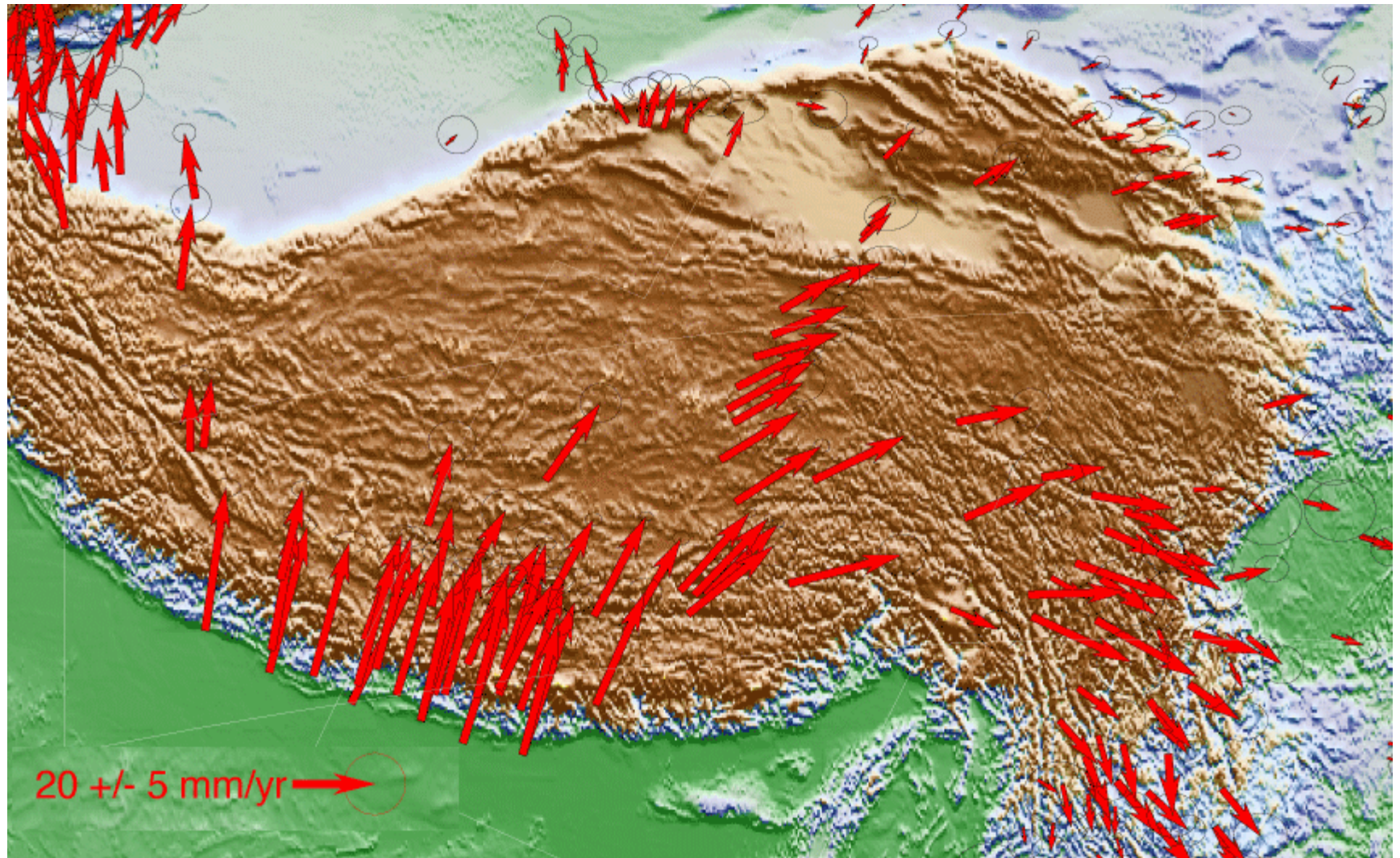
One year of postseismic deformation: Average velocities are 20-25 times faster than before the earthquake



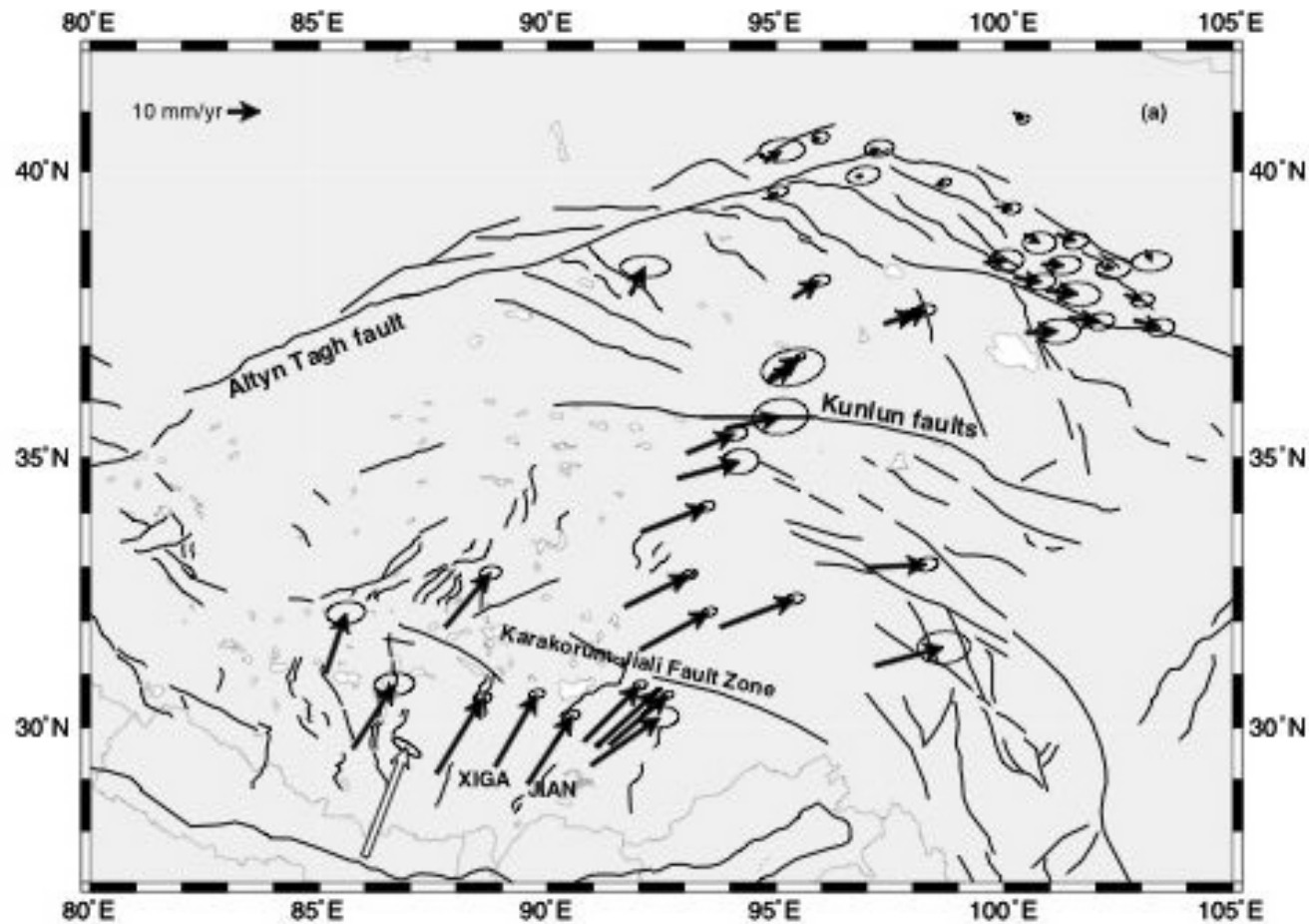




Tibet Velocities



Velocities Relative to Eurasia



Chen et al. (2004), JGR

Displacement and Strain

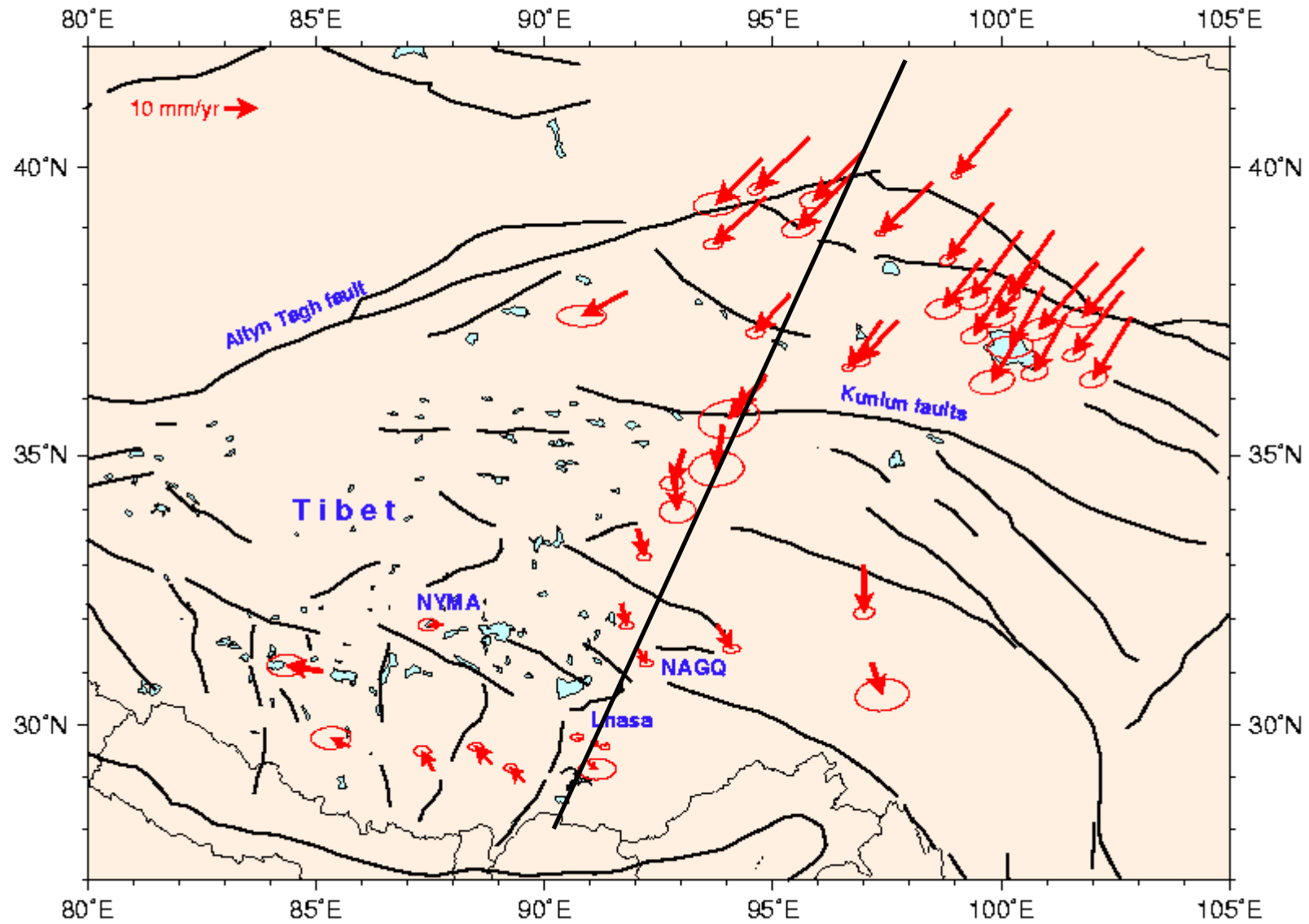
- Displacements (or rates) are a combination of rigid body translation, rotation and internal deformation

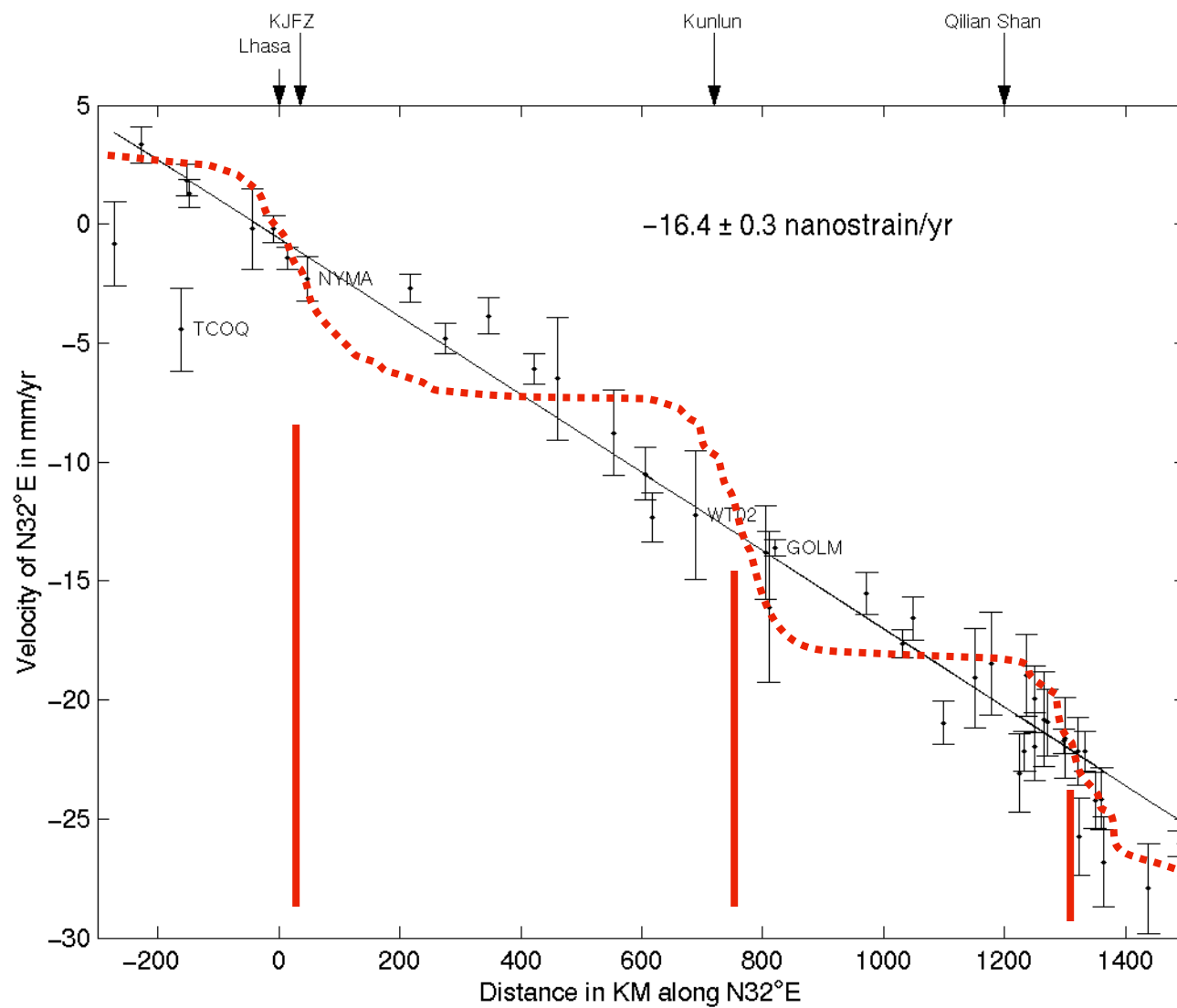
$$\begin{bmatrix} v_{east} \\ v_{north} \end{bmatrix} = \begin{bmatrix} v_{e,body} \\ v_{n,body} \end{bmatrix} + \begin{bmatrix} \dot{\epsilon}_{11} & \frac{1}{2}(\dot{\epsilon}_{12} + \dot{\omega}) \\ \frac{1}{2}(\dot{\epsilon}_{12} - \dot{\omega}) & \dot{\epsilon}_{22} \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

ϵ = strain tensor components
 ω = rotation

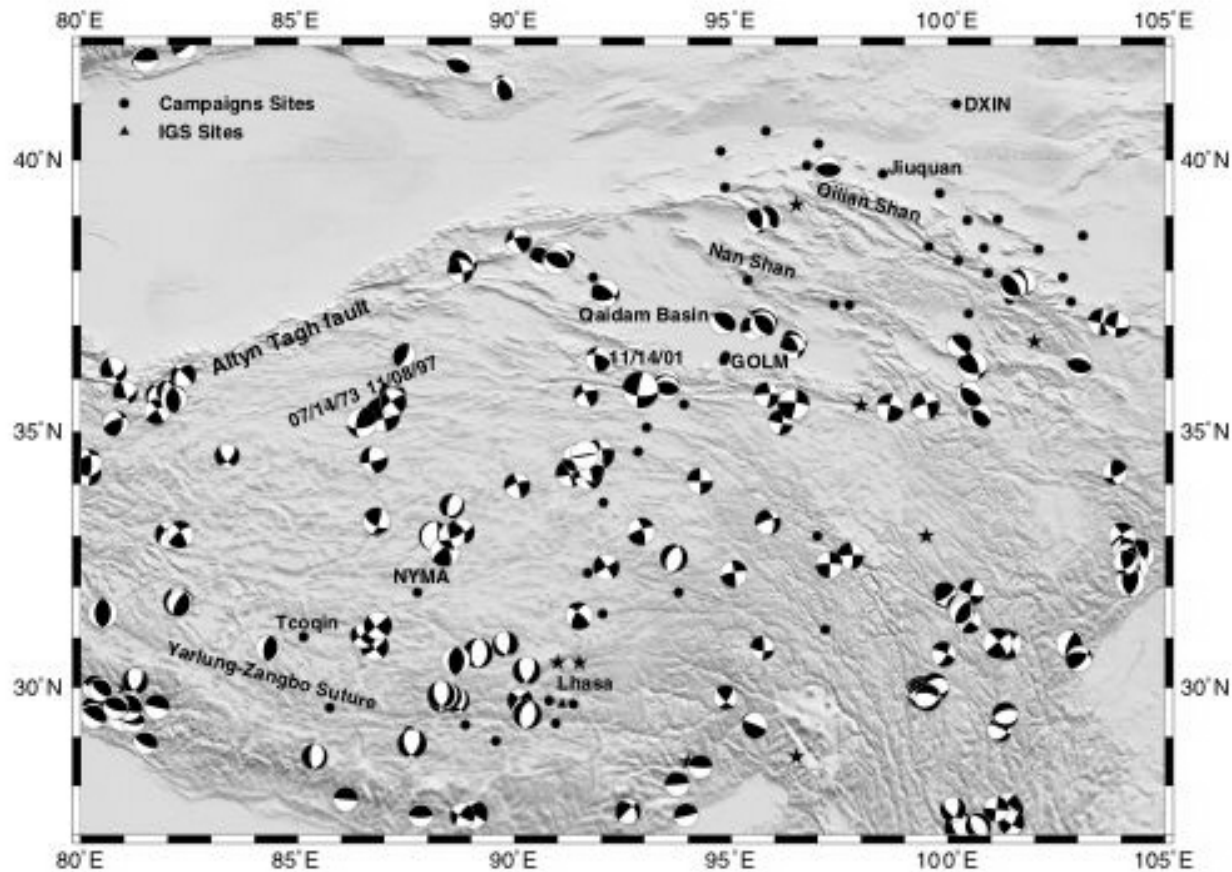
(x, y) = position
 \mathbf{v} = velocity

Velocity Field Relative to Lhasa

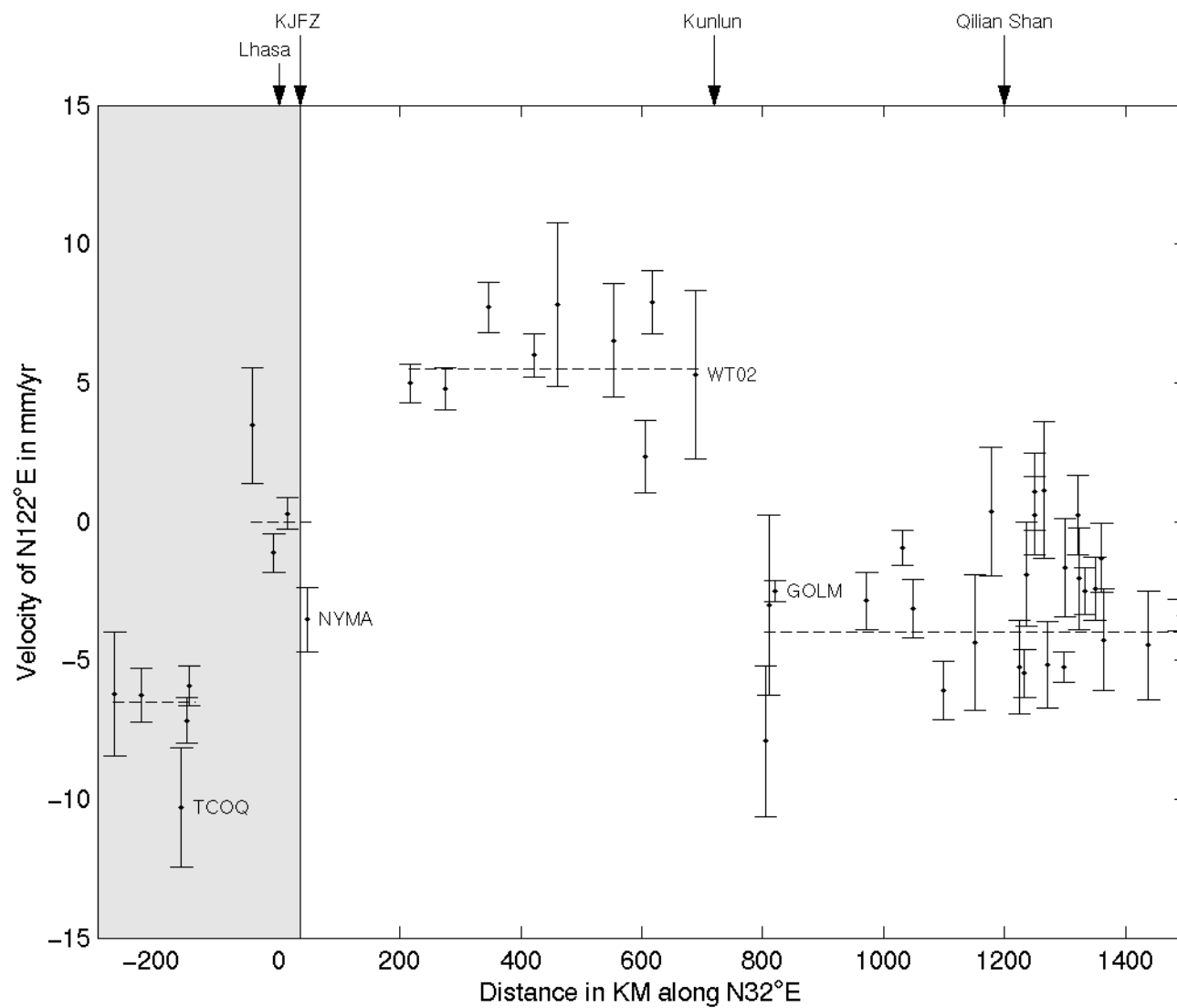




No Thrust Faults Within Plateau



Coupled ~E-W extension and ~N-S contraction via N-S normal and distributed conjugate strike-slip faulting

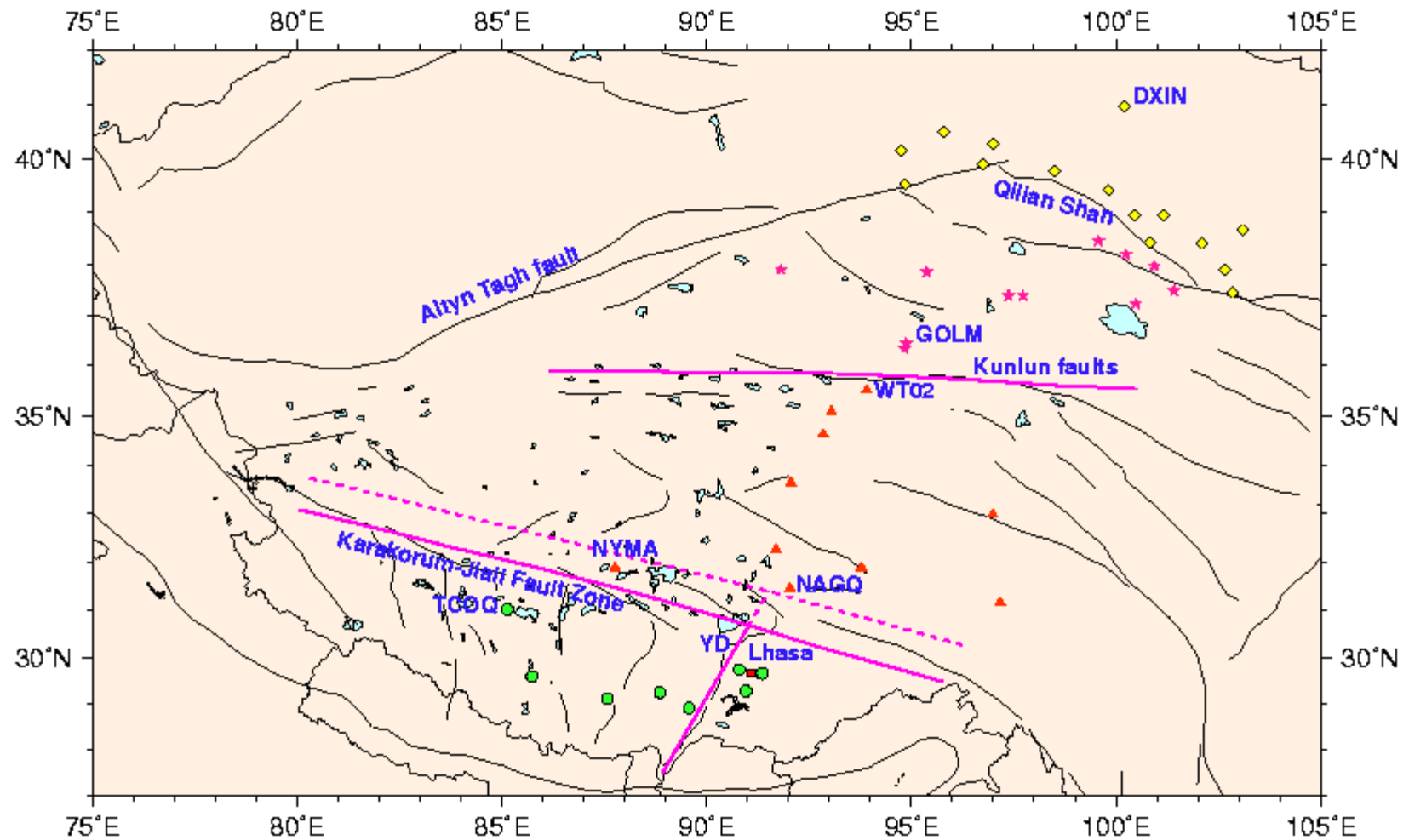


Blocks or Continuum?

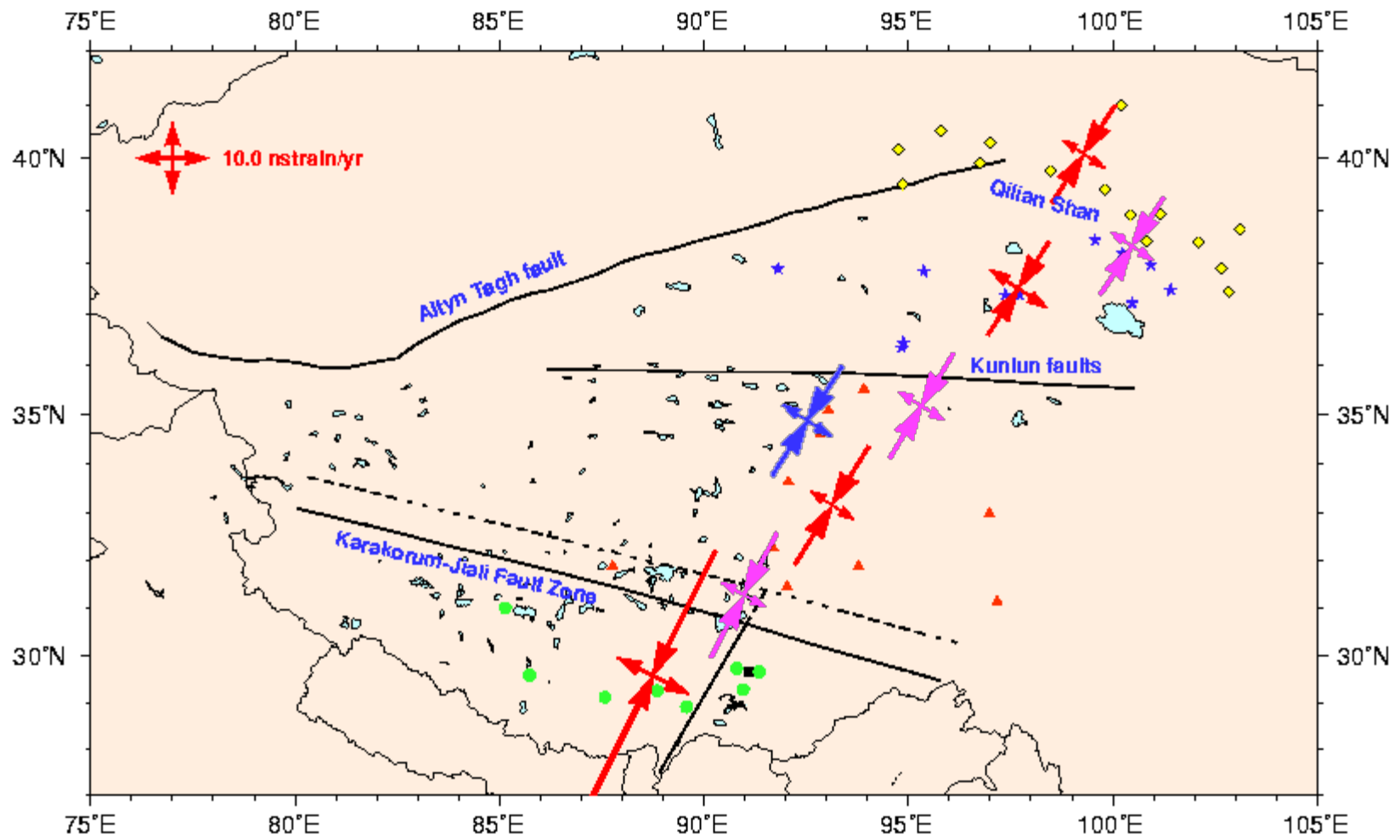
- N32°E component resembles continuum deformation
 - Possibly continuum deformation
 - or distributed slip on many small faults
- N122° component resembles quasi-rigid block motion
- Both at the same time? How can this be?

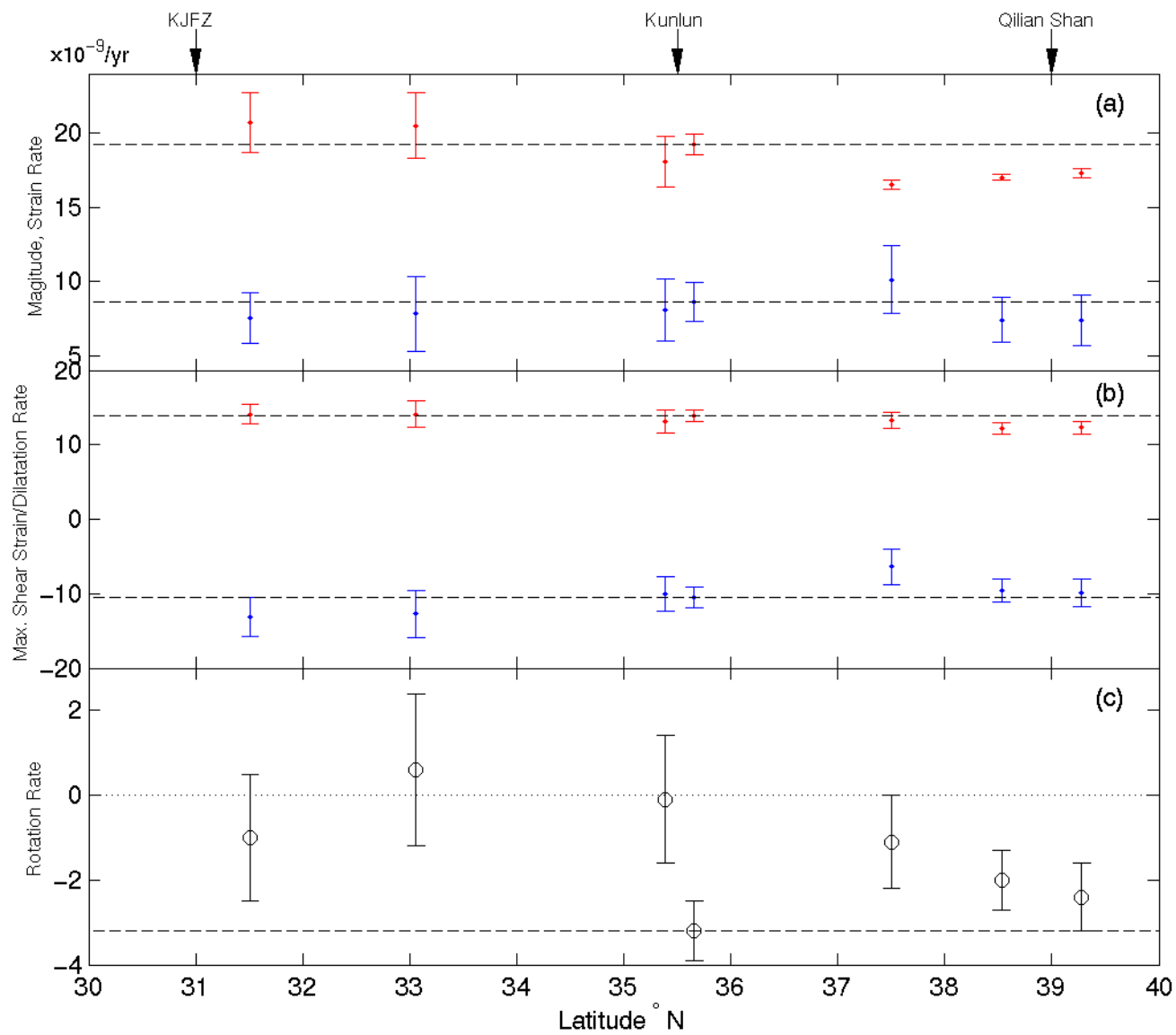
What if blocks are not rigid, but instead deform internally?

Block Boundaries



Uniform Strain Rate

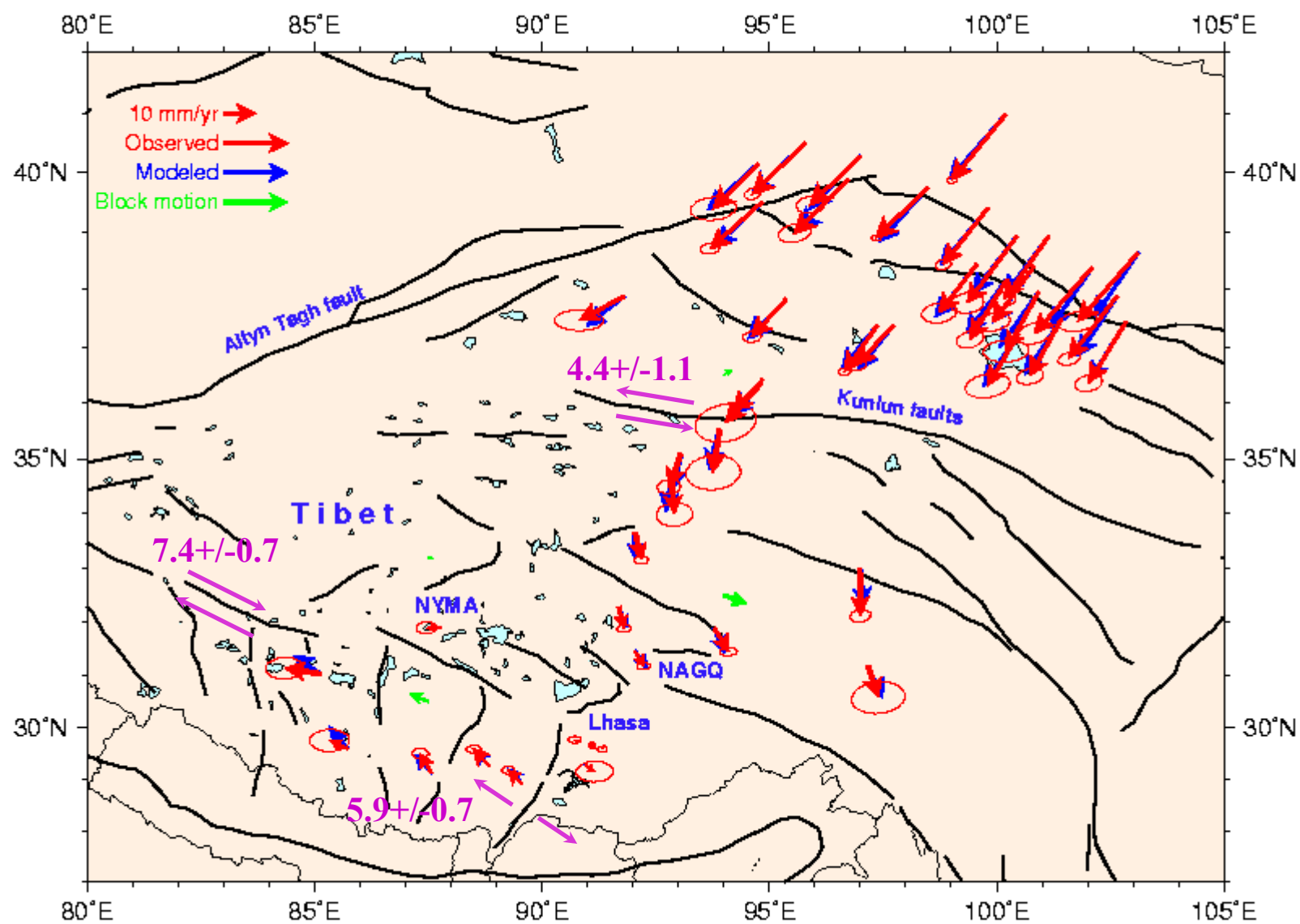


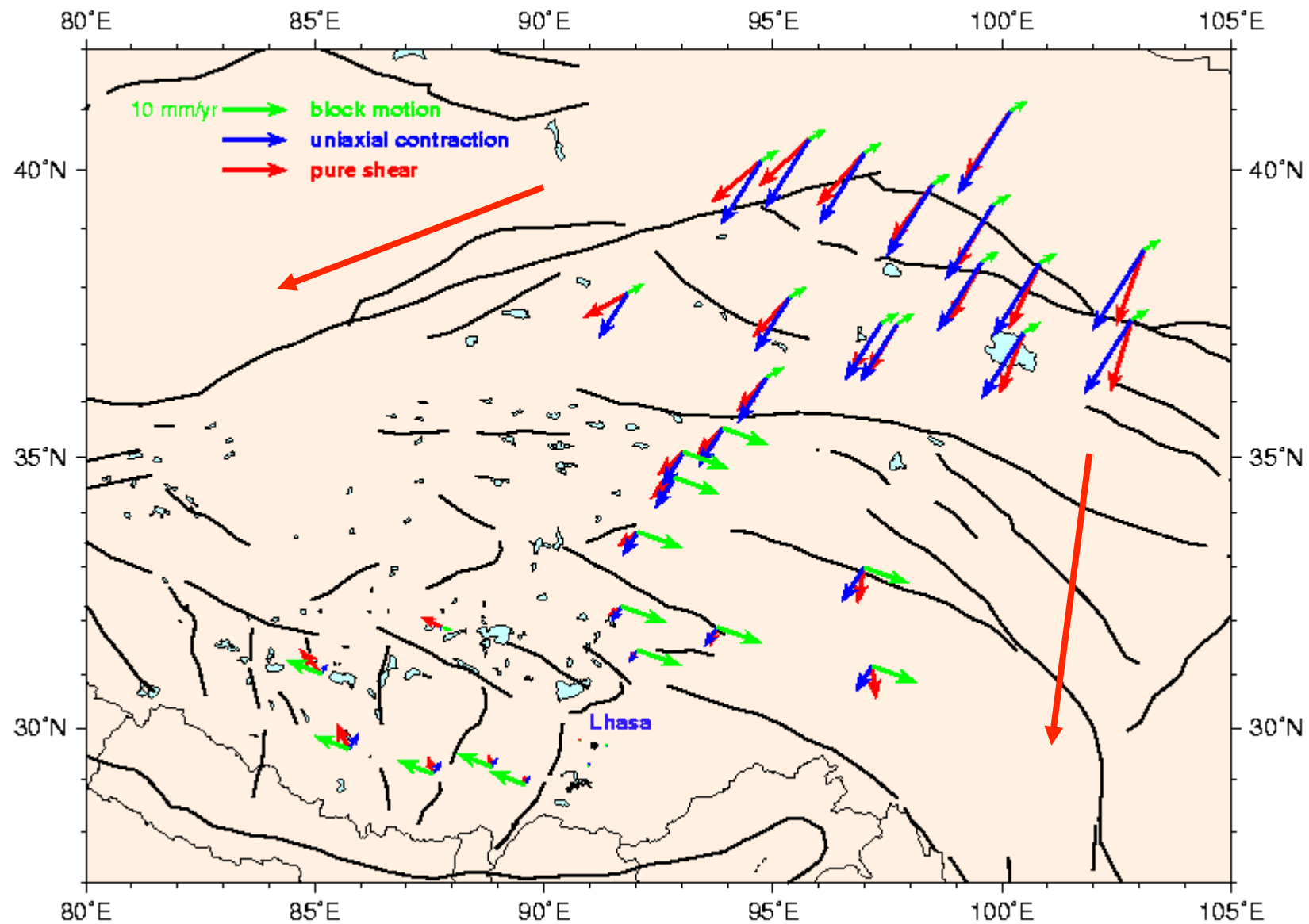


$$\begin{pmatrix} \dot{\epsilon}_1 & 0 \\ 0 & \dot{\epsilon}_2 \end{pmatrix} = \dot{\epsilon}_2 \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix} + \dot{\epsilon}_1 \begin{pmatrix} -1 & 0 \\ 0 & 0 \end{pmatrix}$$

Deforming Block Model

- Based on GPS data from 44 sites
- Four blocks moving relative to each other on major faults, plus uniform strain
 - Block motions are predominantly strike-slip
- Models with spatial variations in strain do not fit significantly better than uniform strain
- Models with all slip concentrated on a few faults fit worse than the deforming block model.





Chen et al. Deforming Block Model

